



# Overview of Deep Learning

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# Artificial Intelligence (AI)

Machines exhibiting animal or human intelligence

Ants bridging algo



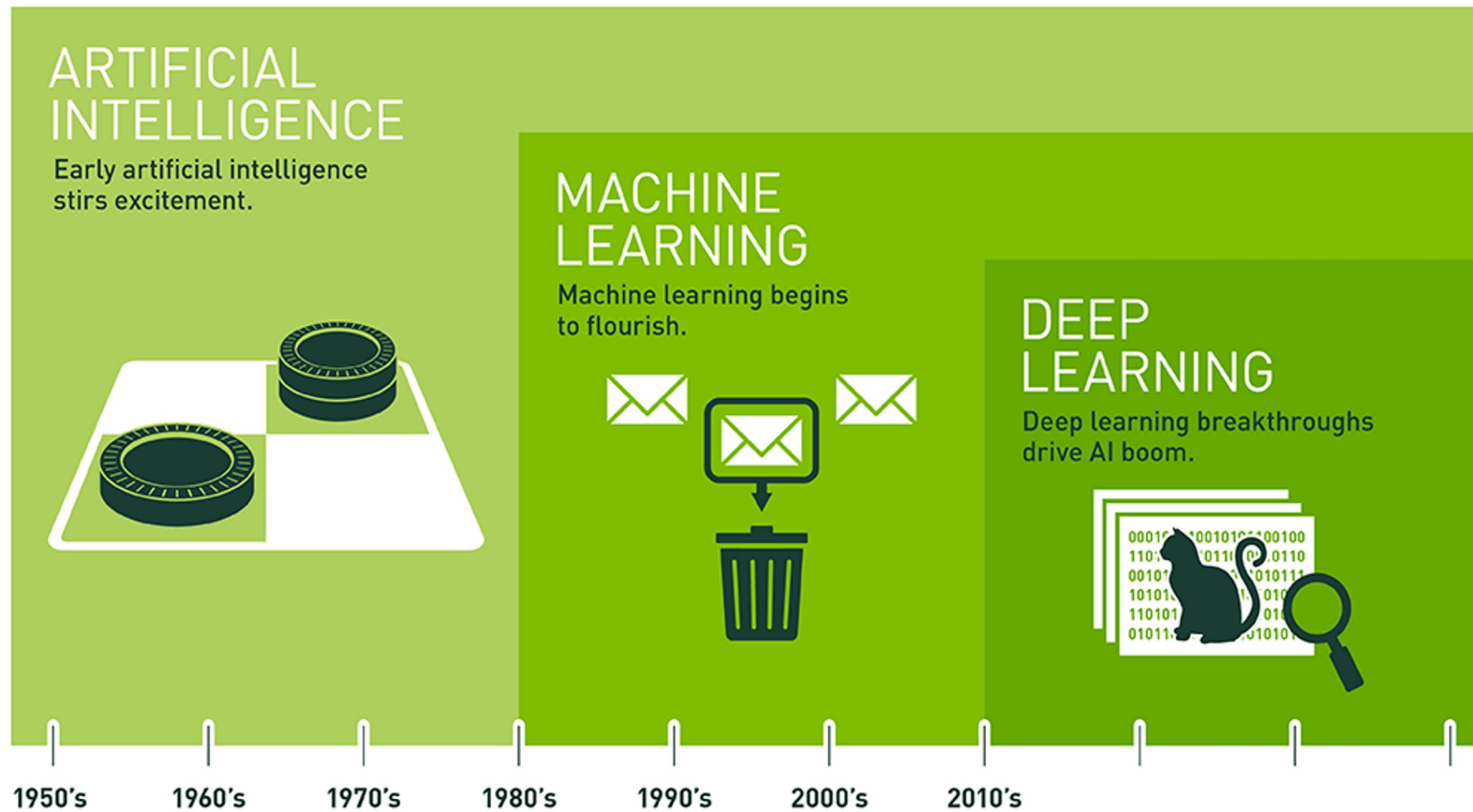
<https://www.quantamagazine.org/the-simple-algorithm-that-ants-use-to-build-bridges-20180226>

# Intelligence

- A very general mental capability that among other things involves the ability to:
  - Reason
  - Plan
  - Solve problems
  - Think abstractly
  - Comprehend complex ideas
  - Learning quickly and learning from experience

Journal of Intelligence 1997 Vol 24 No 1

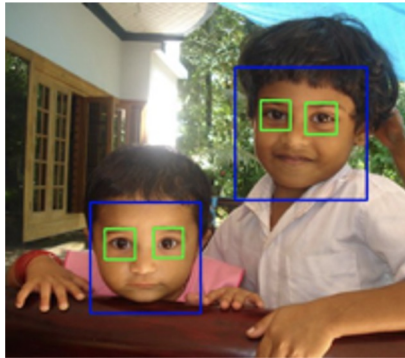
# AI, Machine Learning and Deep Learning



NVIDIA

Since an early flush of optimism in the 1950s, smaller subsets of artificial intelligence – first machine learning, then deep learning, a subset of machine learning – have created ever larger disruptions.

# Artificial Intelligence, Machine Learning and Deep Learning on Face Detection

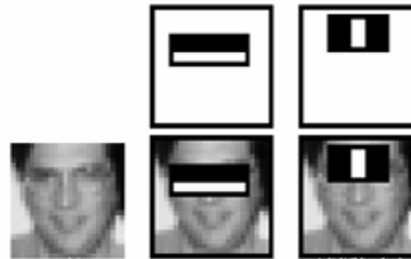


## Rule-based (AI):

Detect facial features based on color/template

**Apply if-else-if-else**

[Viola & Jones 2001]

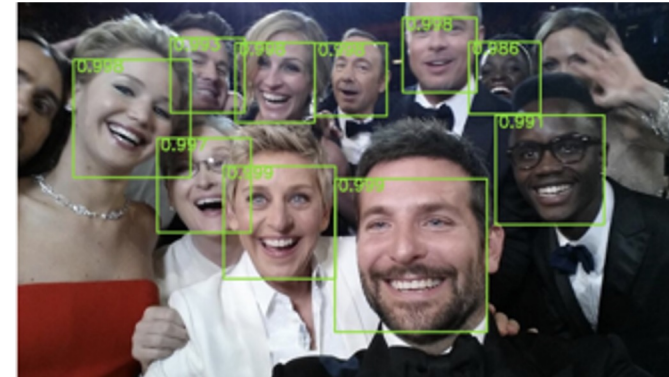


## Machine Learning:

Use Haar Cascade Classifier

**Hand-crafted feature detection**

YOLO, SSD, RCNN [>2012]



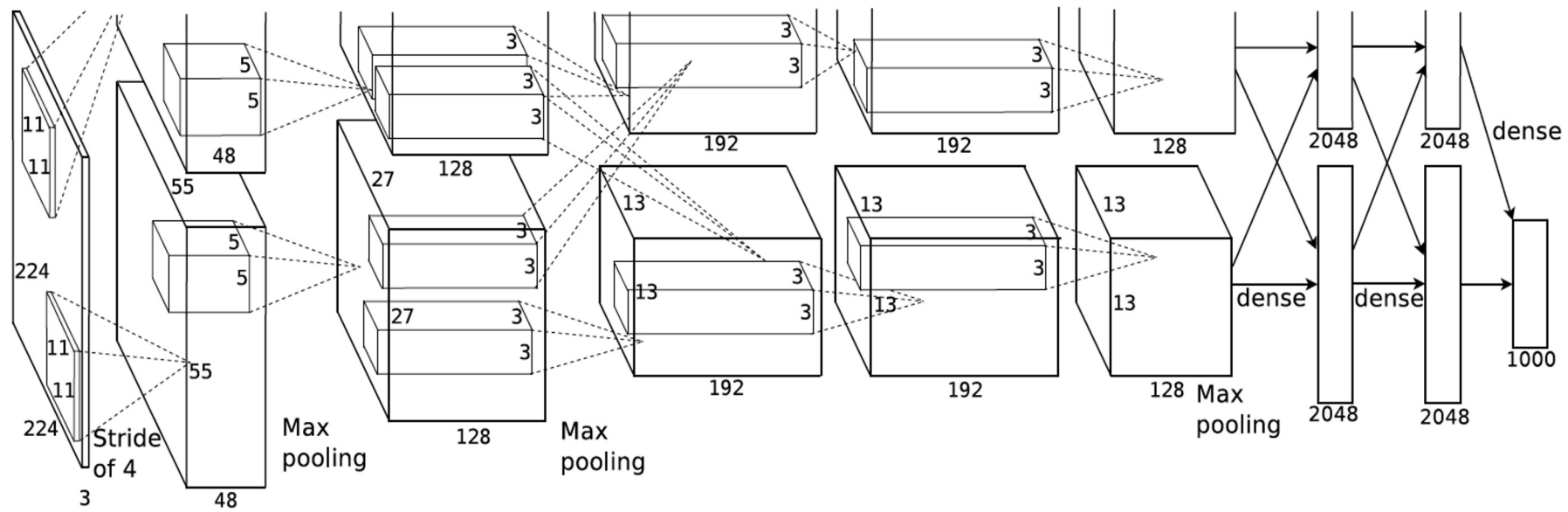
## Deep Learning:

Train a network by showing thousands of labelled region of faces

**Automatic feature detection**

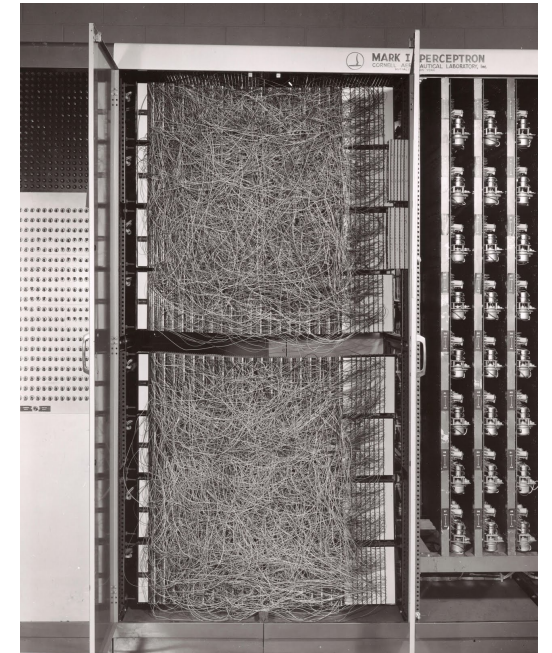
# Deep Learning Moment - 2012

- AlexNet – 650,000-neuron deep neural network won 2012 ImageNet1k competition with 15% Top-5 error rate compared to 2<sup>nd</sup> place with 26%. It's top 1 accuracy is 63.3%.



# Deep Learning - what made it work?

- Concepts of artificial neural network (ANN) and convolutional neural network (CNN) are old
  - Neurons in perceptron (1-layer NN) – 1958
  - Neocognitron (1980) and CNN (1989)
  - Backpropagation (1986)
- What's new?
  - Computing power – Massive number of GPU CUDA cores
  - Data – from the Internet



Perceptron is a binary classifier



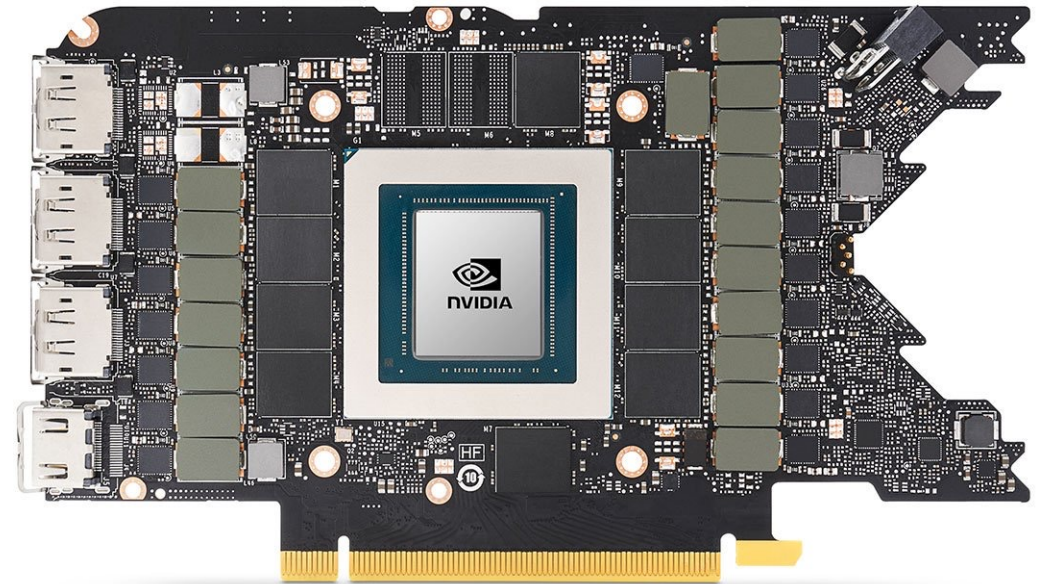
CPU (AMD RyZen)

vs

GPU (RTX 3090)



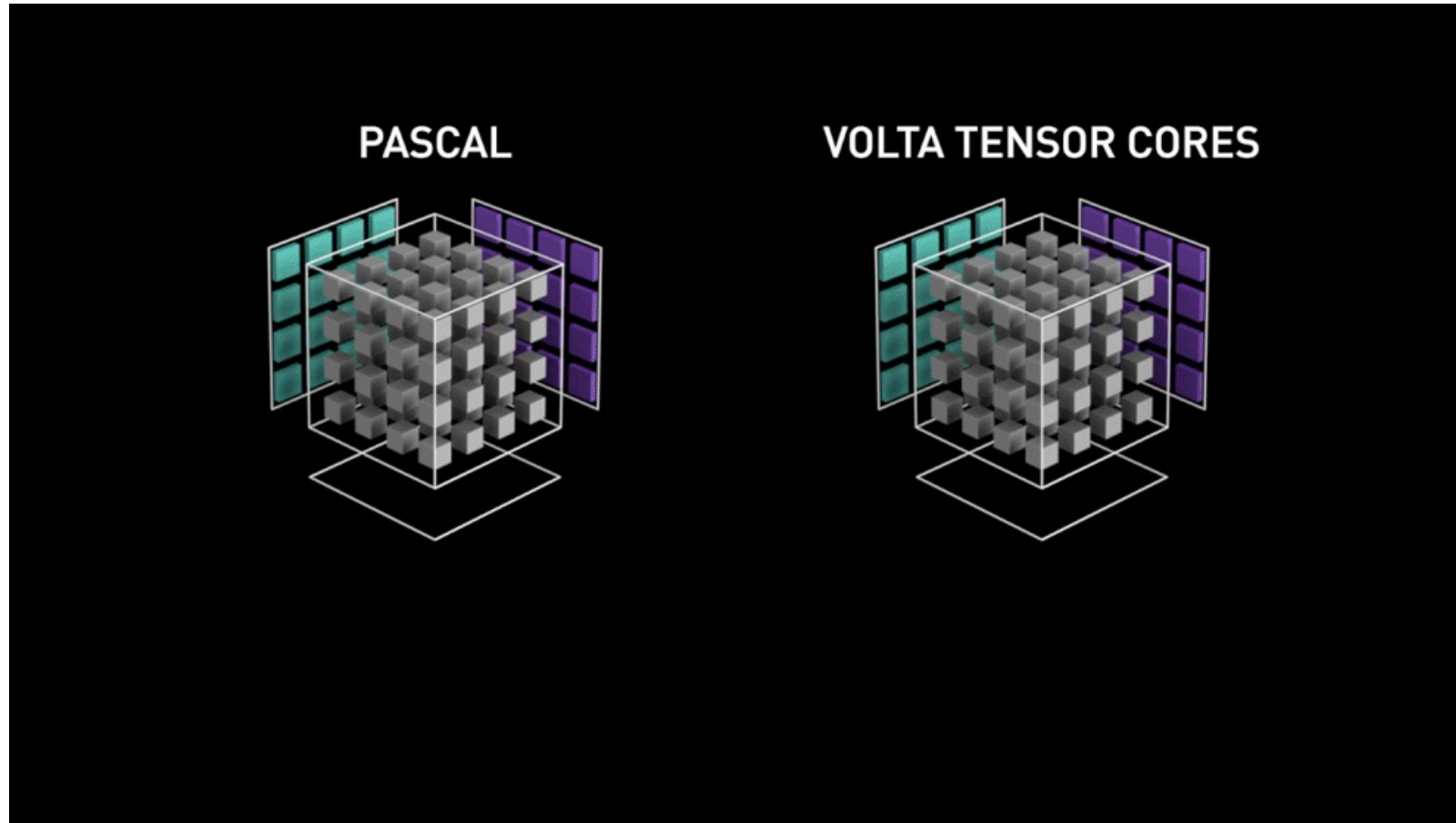
64 3.7GHz super fast cores  
6.9 TFLOPS



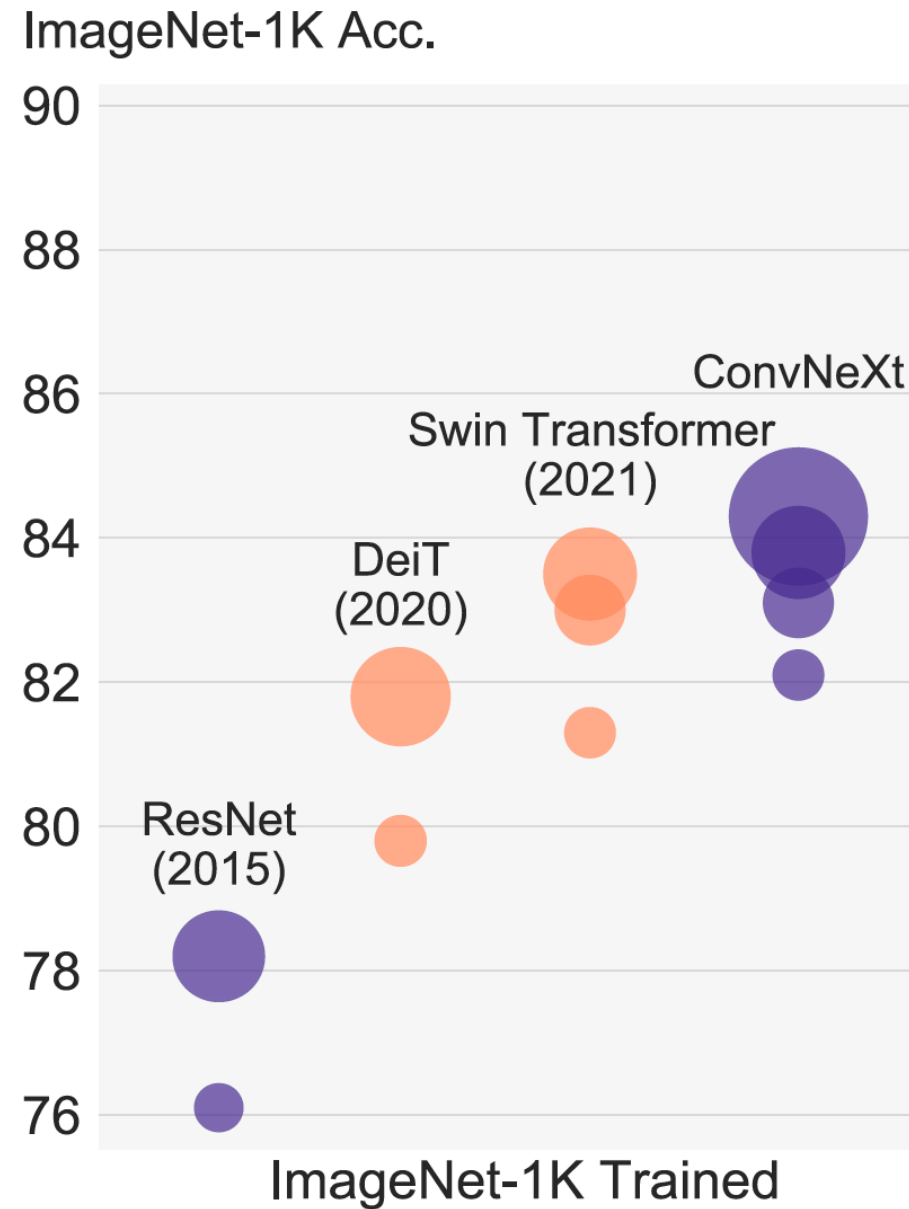
10,496 1.4GHz fast cores  
35.6 TFLOPS



# 1D vs 2D Tensor Operation

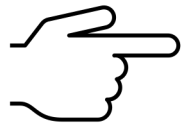


# The Rest is History



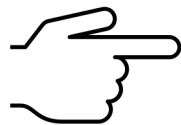
# Barely scratching the surface of Artificial General Intelligence (AGI)

Starting to move here



*Doing* :  $p(y|do(x))$

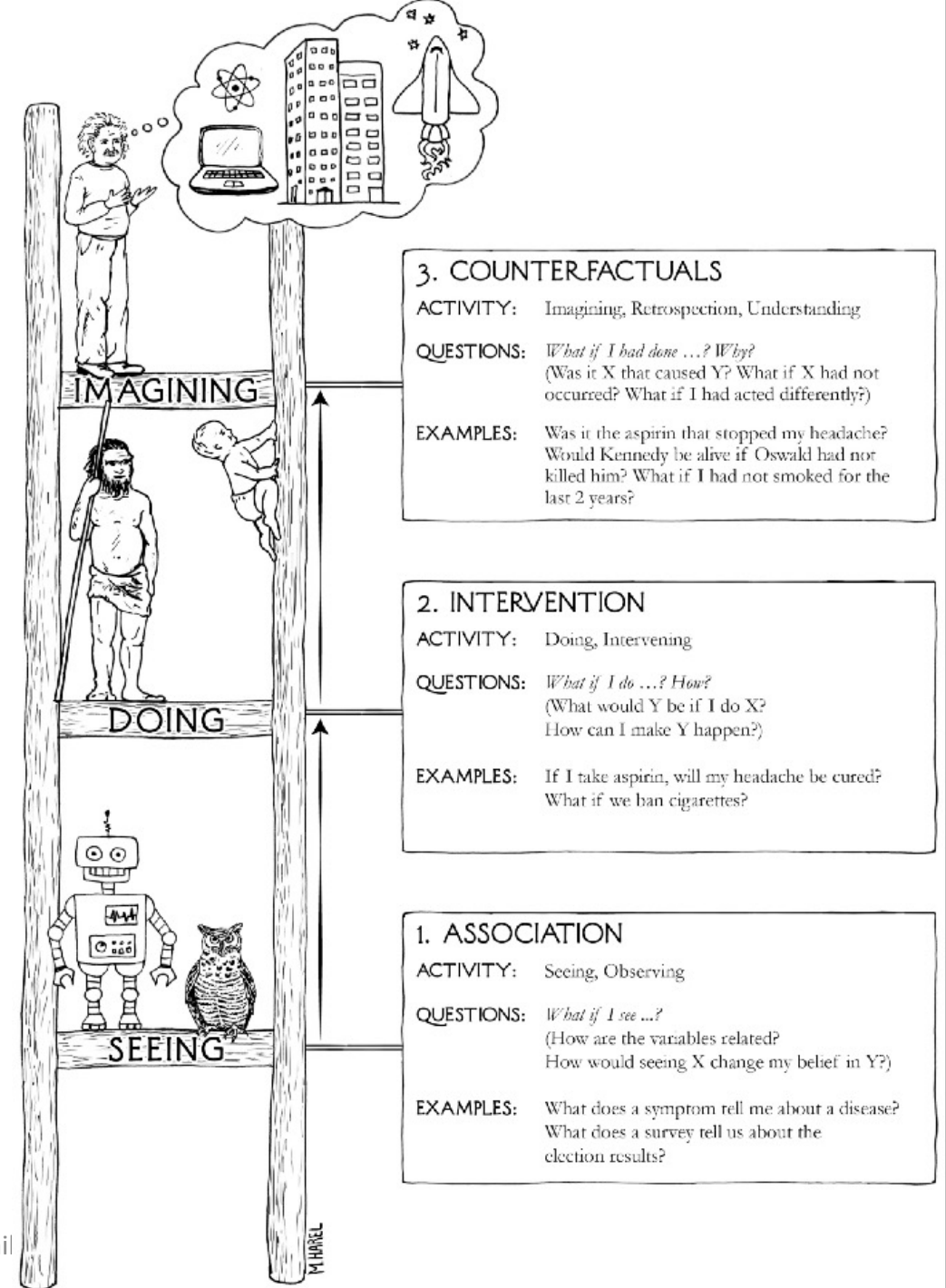
We are here



*Seeing*:  $p(y|x)$

Pearl, Book of Why

*Imagining*



Does ChatGPT (or LLMs in general) exhibit AGI?

# Do Large Language Models Perform Reasoning in Problem Solving Tasks?

# Comprehensive Tests

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## **Faith and Fate: Limits of Transformers on Compositionality**

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# GPT4 Reasoning Test



What is  $3 \times 567$  ?



The product of 3 and 567 is 1701.



What is  $3 \times 5678$  ?



The product of 3 and 5678 is 17034.



What is  $3 \times 56789$ ?



The product of 3 and 56789 is 170367.



What is  $345 \times 56789$ ?



The product of 345 and 56789 is 19,577,205.



What is  $345 / 56789$ ?



The result of 345 divided by 56789 is approximately 0.006072.



What is 4 raised to its square?



Raising a number to the power of its own square is a sizable operation. In this case, you're asking what is  $4^{(4^2)}$ , or  $4^{16}$ .

$4^{16}$  equals 18,446,744,073,709,551,616.

Failed!



```
>>> import math
>>> math.pow(4, 16)
4294967296.0
```

# How Humans use Reasoning to Solve Tasks

- Break a problem into sub-tasks
- A sub-task is a node
- Solving a sub-task transitions it into a new sub-task
- Repeat until all sub-tasks are completely solved

## Computation Graph!

*Sub-task - Vertex*

*Solution – Edge or Operator*

# Computation Graph for Multiplication Algo

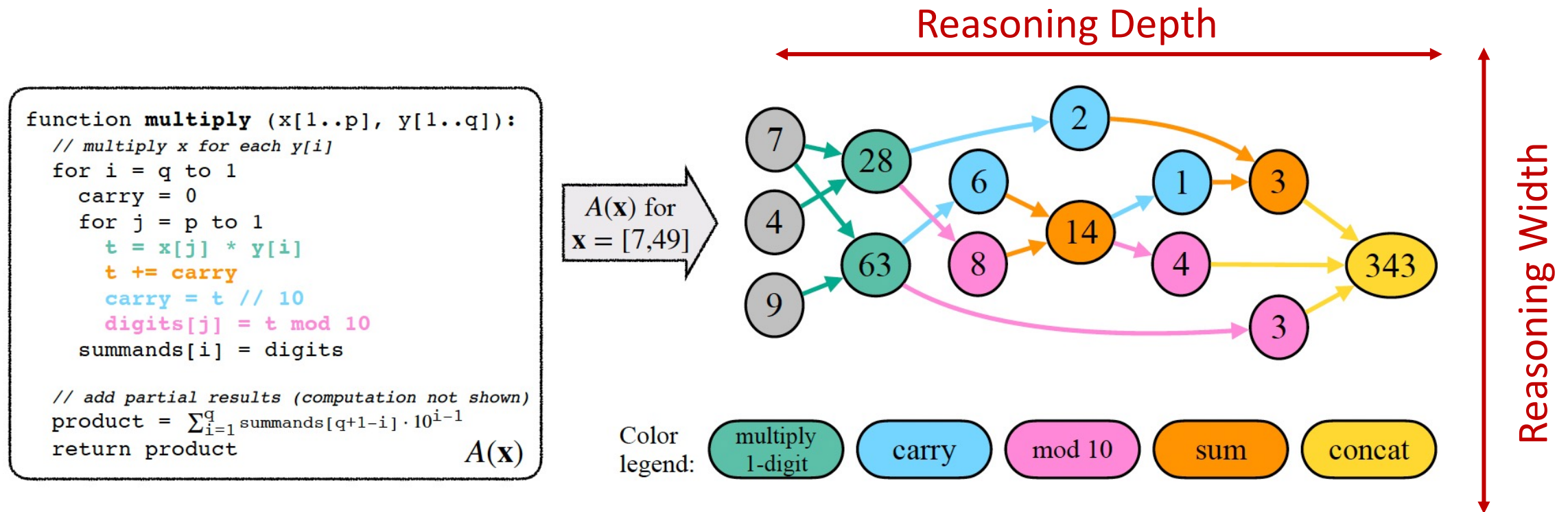
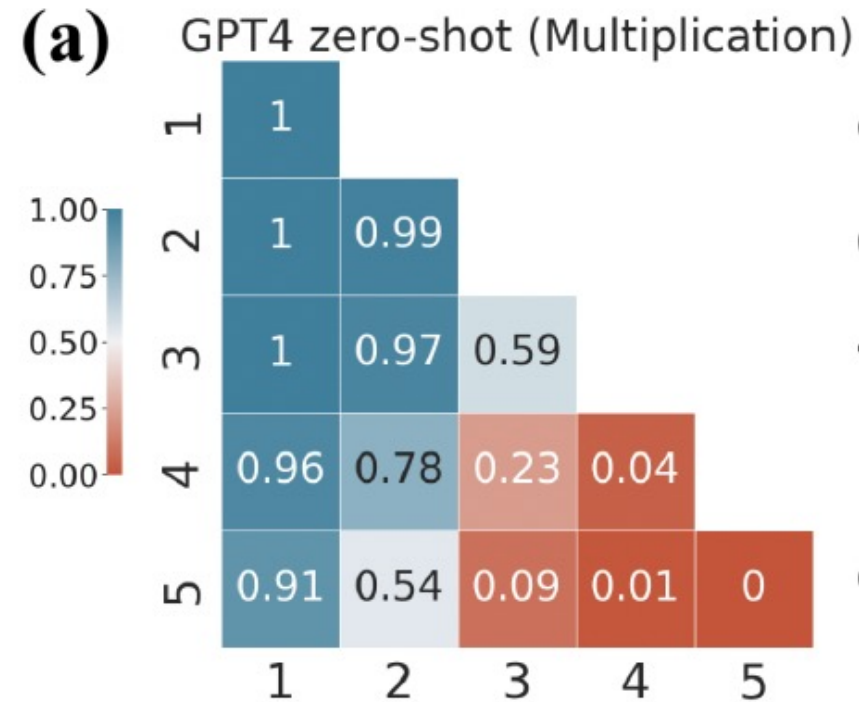


Figure 1: Transformation of an algorithm  $A$  to its computational graph  $G_{A(x)}$ . The depicted example is of long-form multiplication algorithm  $A$ , for inputs  $x = [7, 49]$  (i.e. computing  $7 \times 49$ ).

# GPT4 Zero-shot Multiplication



*No longer applies as demonstrated in the previous slides!*

# Relative Information Gain (RIG)

$$\text{RelativeIG}(Y_j, X) = \frac{H(Y_j) - H(Y_j|X)}{H(Y_j)} \in [0, 1]$$

$Y_j$  : output

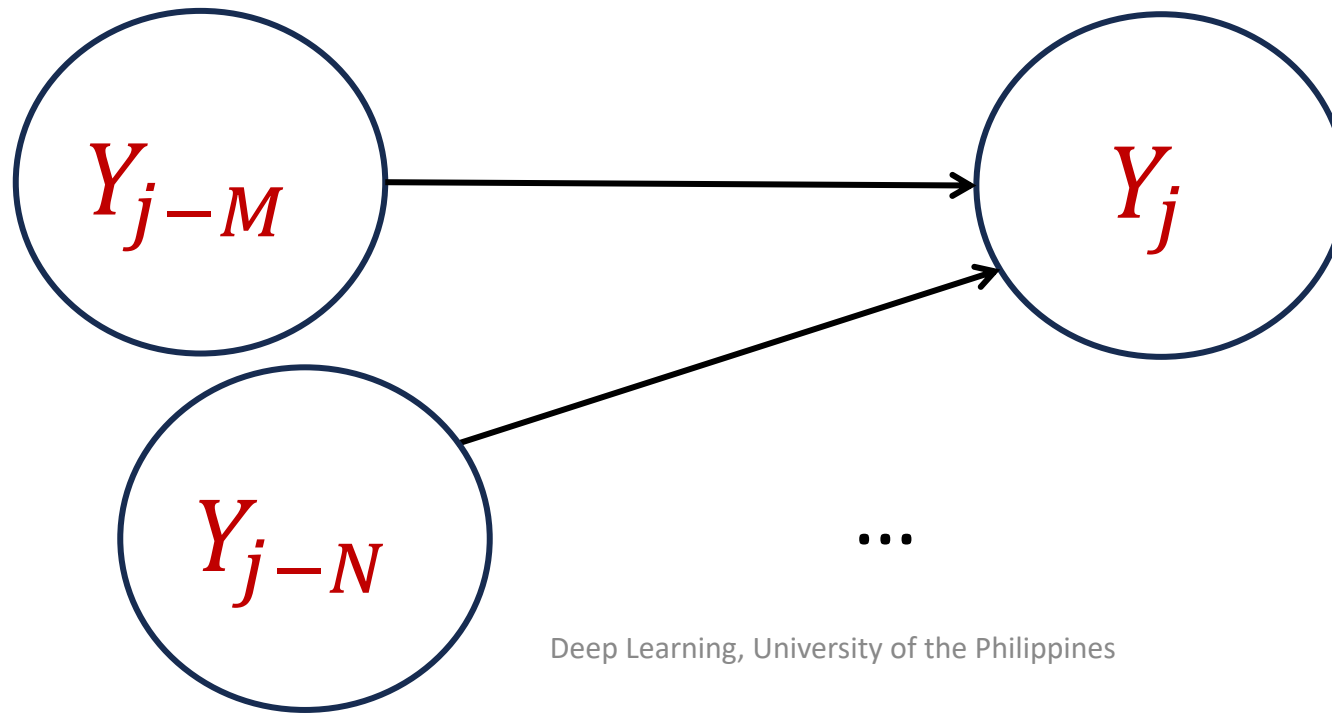
$X$  : input random variables

$H(Y) = -\mathbb{E}[\log p(Y)]$  : entropy



# Observation

- LLMs break down a problem into a computational graph
- LLMs can solve problems where the RIG is high between sub-tasks
- When the RIG is low, the LLM hallucinates



## 2 Critical Points

- Ability to break down a problem into a correct computation graph
- High RIG between sub-tasks

# When do LLMs fail?

- In-correct computation graph
- A presence of low RIG between sub-tasks
  - Deep reasoning graphs can amplify errors due to error propagation

# Incorrect computation graphs

- Instruction-based tuning
- Prompt engineering
- Etc

## **InstructBLIP: Towards General-purpose Vision-Language Models with Instruction Tuning**

LARGE LANGUAGE MODELS AS OPTIMIZERS

# Low RIG between sub-tasks

- Higher data quality

**TinyStories:** How Small Can Language Models Be and Still Speak Coherent English?

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**LIMA: Less Is More for Alignment**

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# Improving Reasoning by Grounding the Language Modality



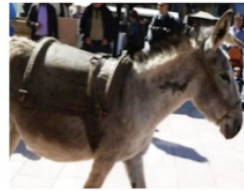
# RT-2: Vision-Language-Action Models Transfer Web Knowledge to Robotic Control

<https://robotics-transformer2.github.io/>



# Pre-train on Internet scale vision-language data

## Internet-Scale VQA + Robot Action Data



Q: What is happening in the image?

A grey donkey walks down the street.



Q: Que puis-je faire avec ces objets?

Faire cuire un gâteau.



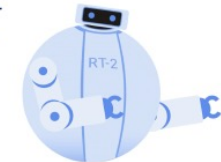
Q: What should the robot do to <task>?

$\Delta$  Translation =  $[0.1, -0.2, 0]$   
 $\Delta$  Rotation =  $[10^\circ, 25^\circ, -7^\circ]$

Co-Fine-Tune

Vision-Language-Action Models for Robot Control

RT-2



Deploy

## Closed-Loop Robot Control



Put the strawberry into the correct bowl

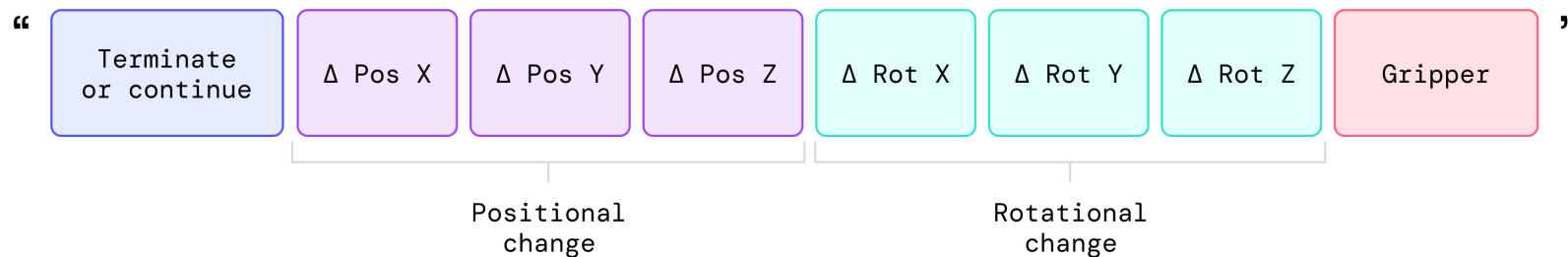
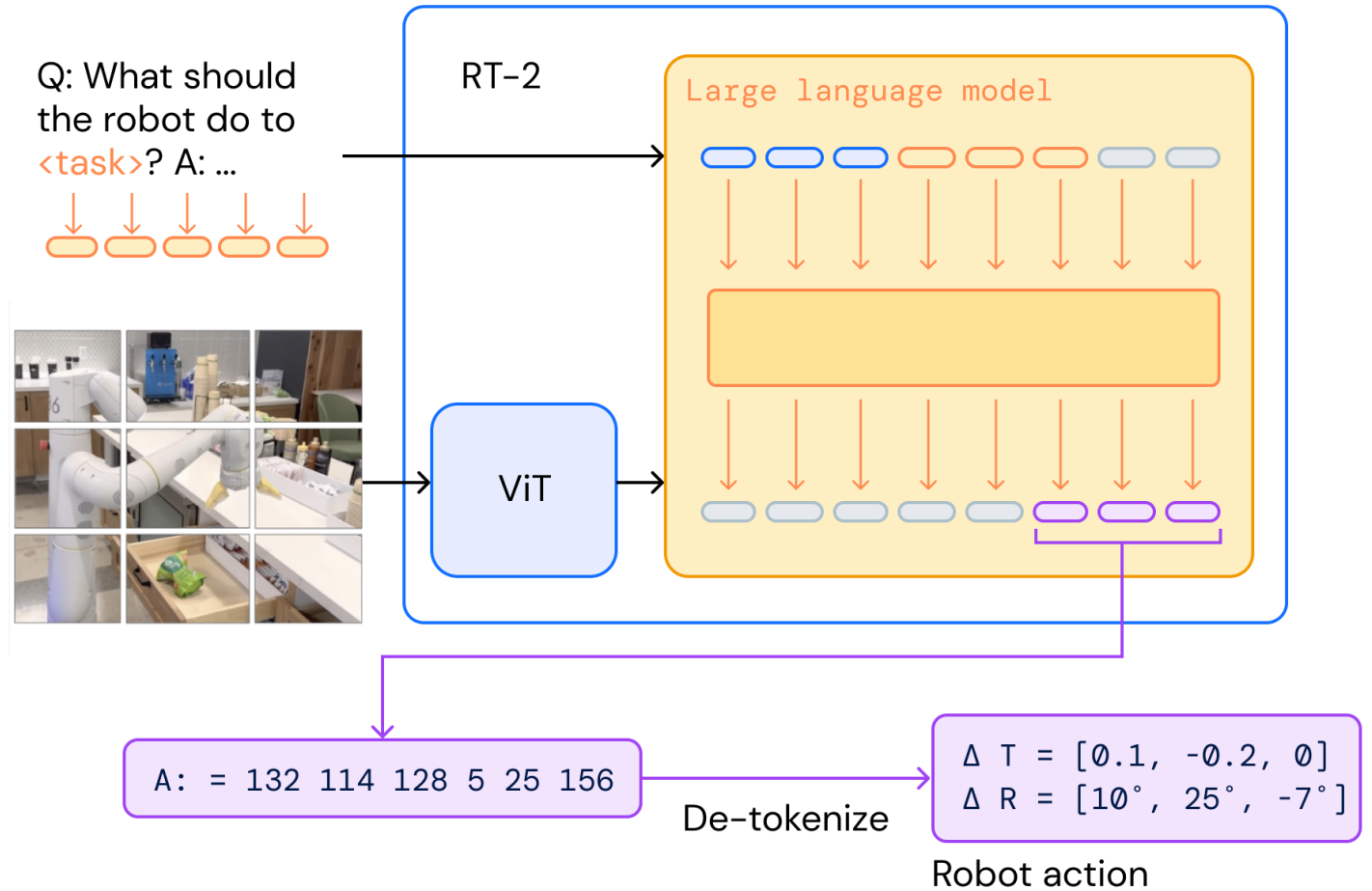


Pick the nearly falling bag



Pick object that is different

Co-fine-tune with real robot data.  
The robot language is used during co-fine-tuning.





# LINGO-1: Exploring Natural Language for Autonomous Driving

<https://wayve.ai/thinking/lingo-natural-language-autonomous-driving/>

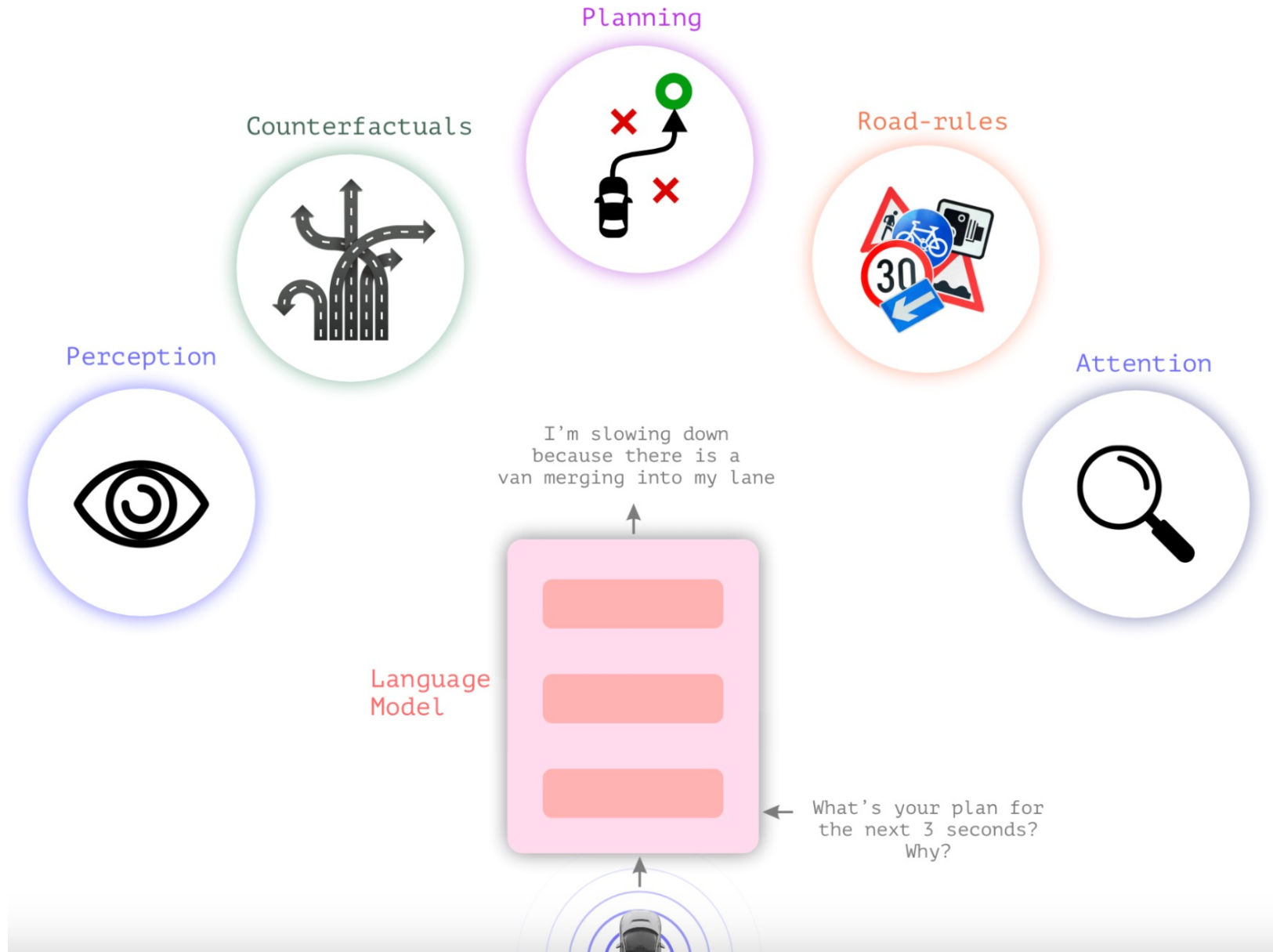


## AV2.0

Bringing the next wave of self-driving technology to market.



# LINGO-1 Architecture





# Lingo-1: Driver Commentator for Autonomous Driving

- slowing down for a lead vehicle or a change in traffic lights,
- changing lanes to follow a route,
- accelerating to the speed limit,
- noticing other cars coming onto the road or stopped at an intersection
- approaching hazards such as roundabouts and Give Way signs,
- parked cars, traffic lights or schools,
- actions other road users are taking, such as changing lanes or overtaking parked vehicles,
- cyclists and pedestrians waiting at zebra crossings or coming up from behind the car in a cycle lane.



WAYVE

Select another segment

replaying model input



London NW Route

Close

● Ready

What do you see?

...

Ask a new question



# LINGO-1 Contributions

- Improved Reasoning due to instructions from driver commentator
- Querying next actions improve model explainability

# References

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