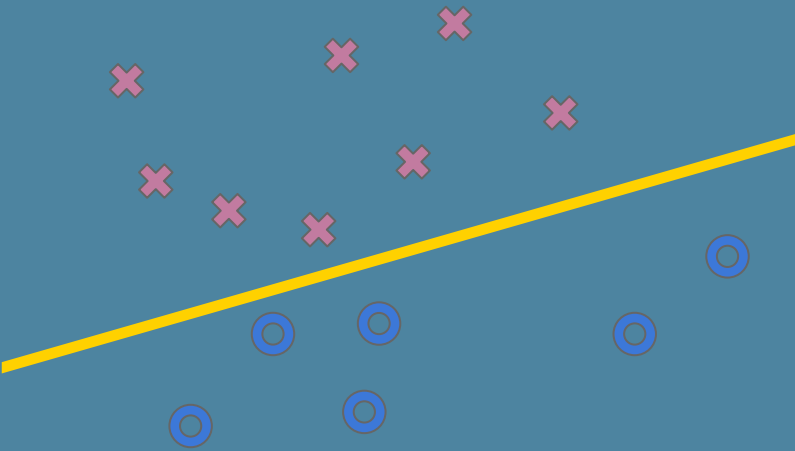


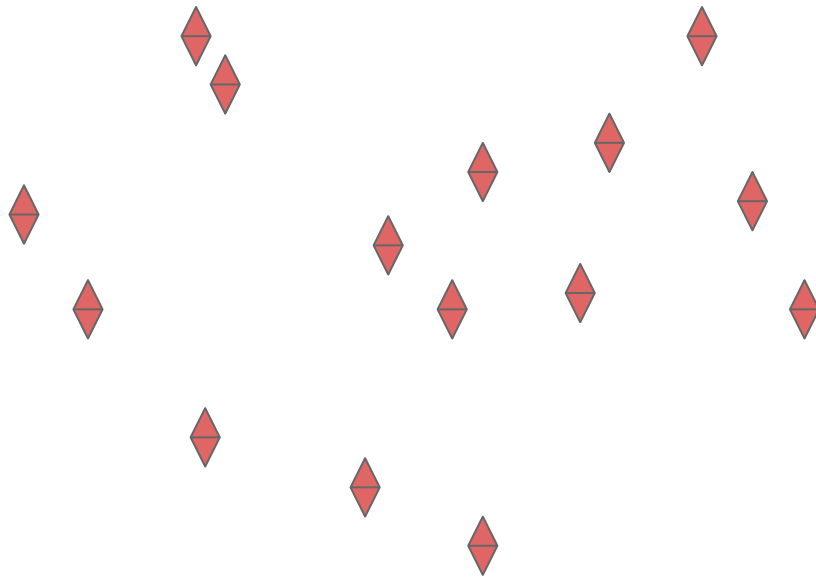
Outline

1. Geometrical machine learning
 - a. Dimensionality curse
 - b. Manifold assumption
2. Dimensionality reduction
 - a. Feature selection
 - b. Multidimensional Scaling (MDS)
 - c. Isomap
 - d. Locally linear embedding (LLE)
 - e. t-SNE
3. Clustering
 - a. k-means
 - b. DBSCAN
 - c. Hierarchical clustering
 - d. metrics
4. Density estimation
 - a. Kernel density estimation

Supervised learning



Unsupervised learning

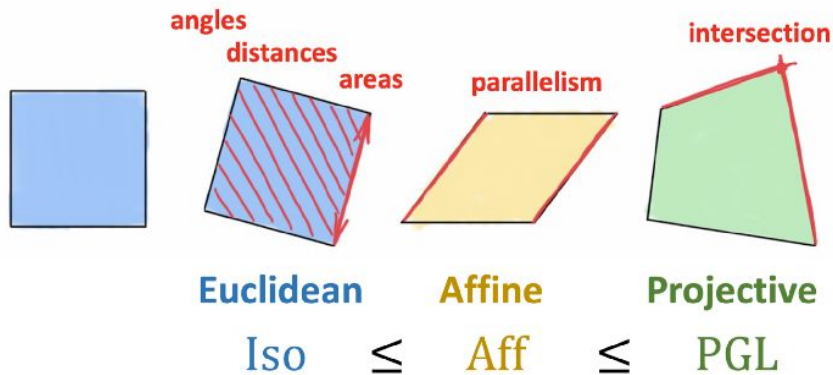


Geometrical machine learning

girafe
ai

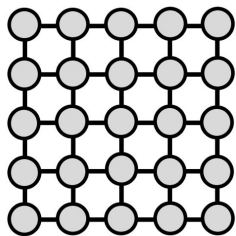
01

Geometrical machine learning

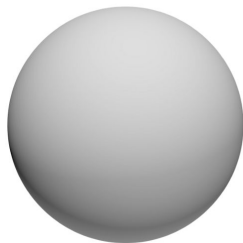


The breakthrough insight of Klein was to approach the definition of geometry as the **study of invariants**, or in other words, structures that are preserved under a certain type of transformations (symmetries)

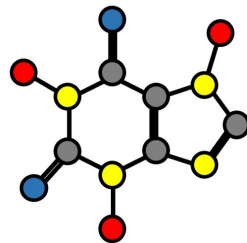
[Article introducing a book on Geometric Deep Learning](#)



Grids



Groups



Graphs

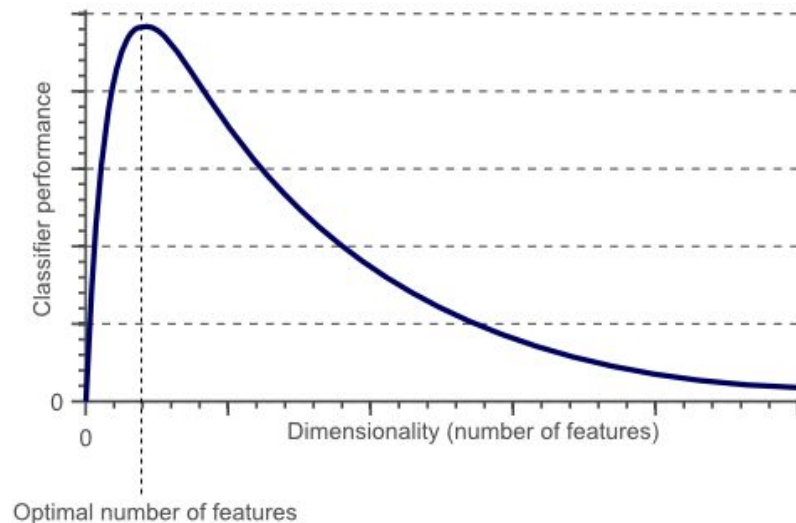


Geodesics & Gauges

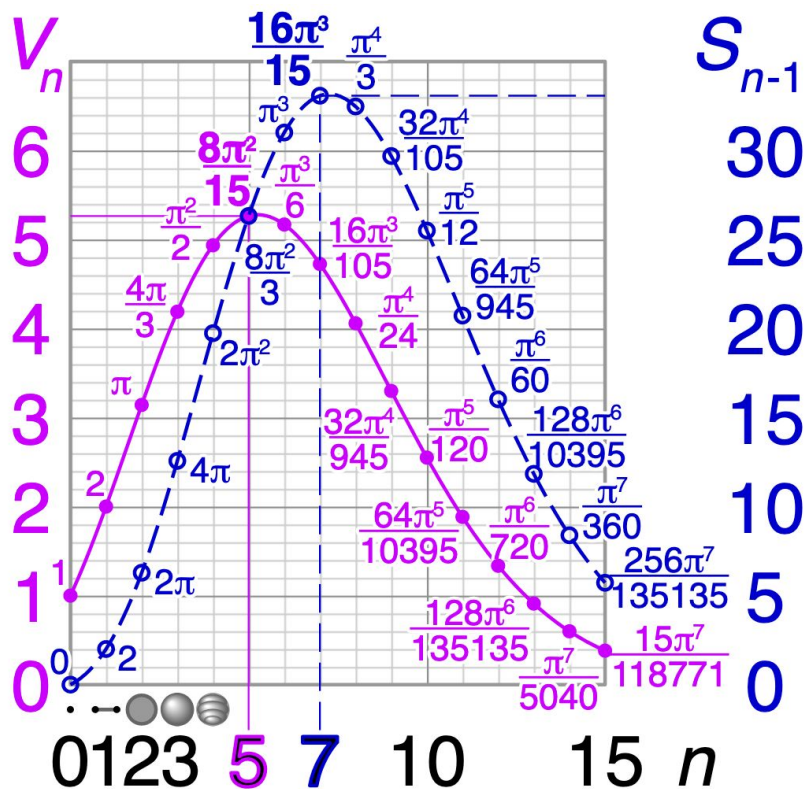
Dimensionality curse



Certain behaviours or effects that appear when analysing data in high dimensions, that do not occur in low-dimensional spaces



Sphere volume decrease

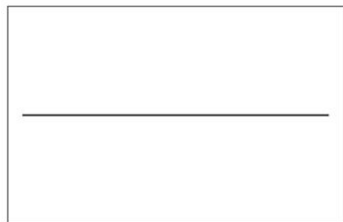


[image source](#)

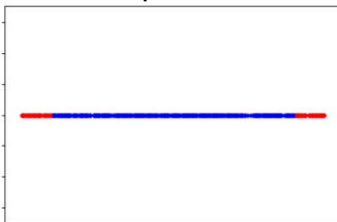
Distance in high dimensional space



Line of length 1



Line with 500 randomly generated points



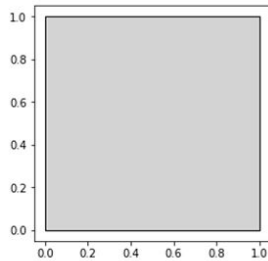
■ Inside points

■ Points that fall within 10% of the distance to the edges

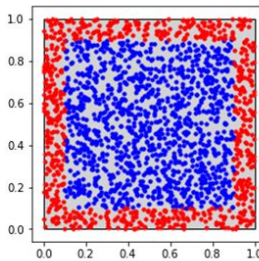
Ratio of inside points to total points = 80%

Average Distance between 2 points = 0.34

Square of side 1



2000 randomly generated points



■ Inside points

■ Points that fall within 10% of the distance to the edges

Ratio of inside points to total points = 63%

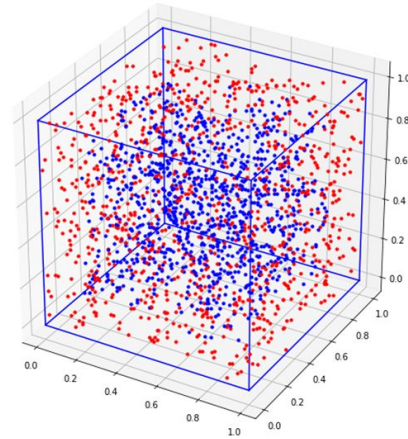
Average Distance between 2 points = 0.52

[image source](#)

Distance in high dimensional space



Cube of side 1



■ Inside points

■ Points that fall within 10% of the distance to the edges

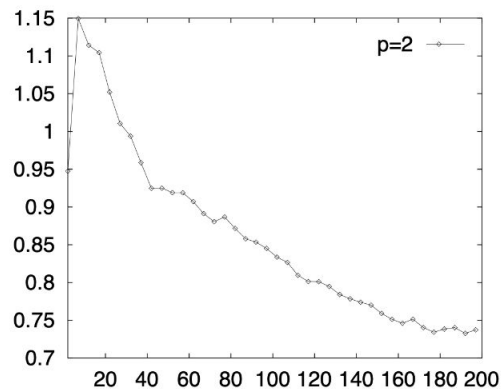
Ratio of inside points to total points = 51%
Average Distance between 2 points = 0.65

Nº of dimensions	% Outside Points	Average distance (A,B)
1	20%	0.34
2	37%	0.52
3	49%	0.65

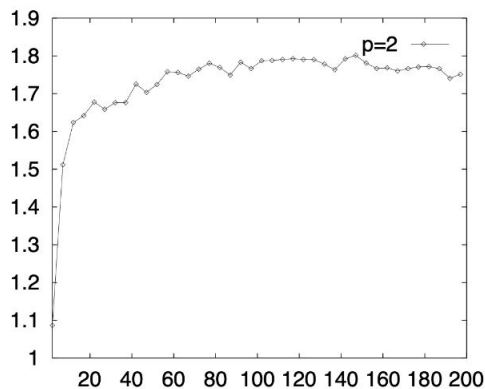
Distance relative contrast



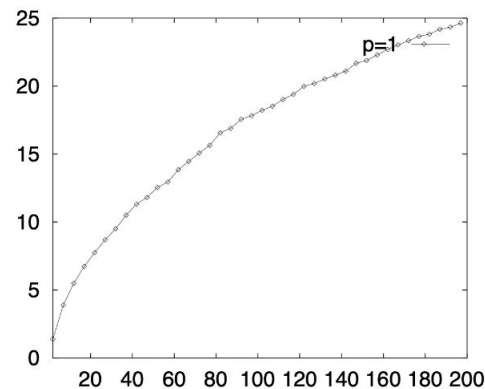
Take random points uniformly distributed in D dimensional cube and calculate distance to the farthest point and to the closest point. Plot their difference depending on D for different Minkowski metrics



L3



L2



L1

[On the Surprising Behavior of Distance Metric in High-Dimensional Space, Aggarwal et al., 2002](#)

Conclusions



- Distance loses its meaning - closest and farthest points are equally far
- Proximity concept becomes ill defined
- Lower powers of Minkowski metrics are more sustainable to dimensionality curse

N° of dimensions	% Outside Points	Average distance (A,B)
1	20%	0.34
2	37%	0.52
3	49%	0.65

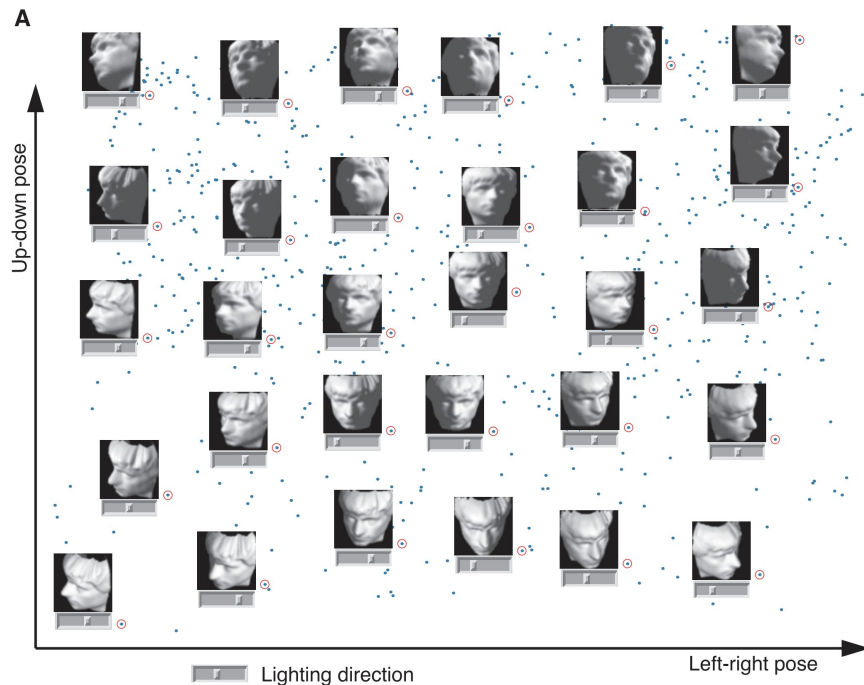
Manifold assumption



The data lie approximately on a surface (called manifold) of usually much lower dimension than the input space

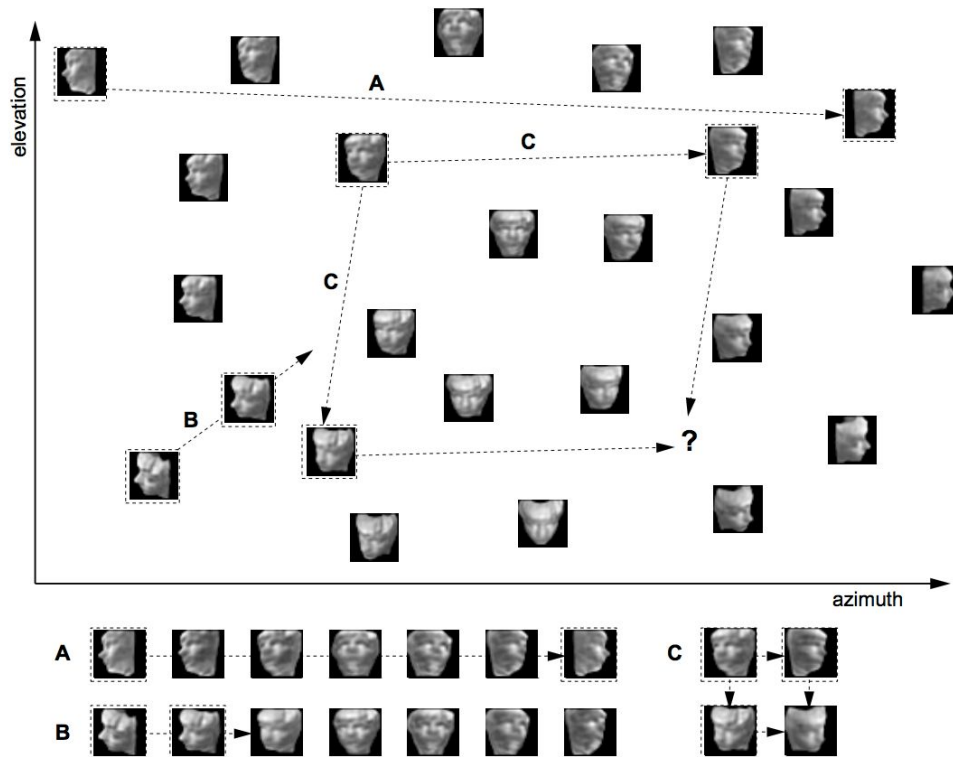
So problem dimensionality could be (non-)linearly reduced or other tasks solved

Sometimes dimensionality of manifold is referred as [intrinsic dimension](#) (see [this article](#))



[Tenenbaum, de Silva, Langford](#)
[A Global Geometric Framework for Nonlinear Dimensionality Reduction](#)

Latent space



Latent (embedding) space describes data in coordinates more relevant to humans' reason and often allows useful linear operations:

- Interpolation (A)
- Extrapolation (B)
- Analogy (C)

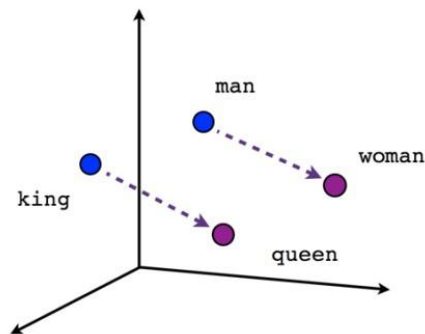
This process is also called embedding space 'walking'



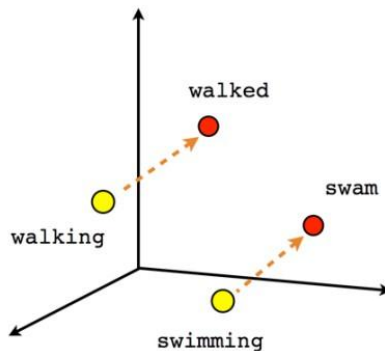
Latent space example

Word2vec is a method to embed words from text corpus into linear space

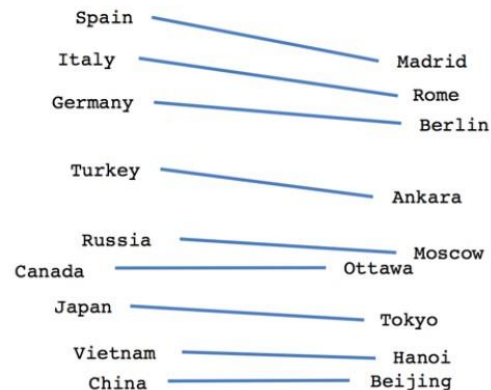
Read more: [manifold assumption](#), [assessing assumption](#)



Male-Female



Verb tense



Country-Capital

Dimensionality reduction

girafe
ai

02

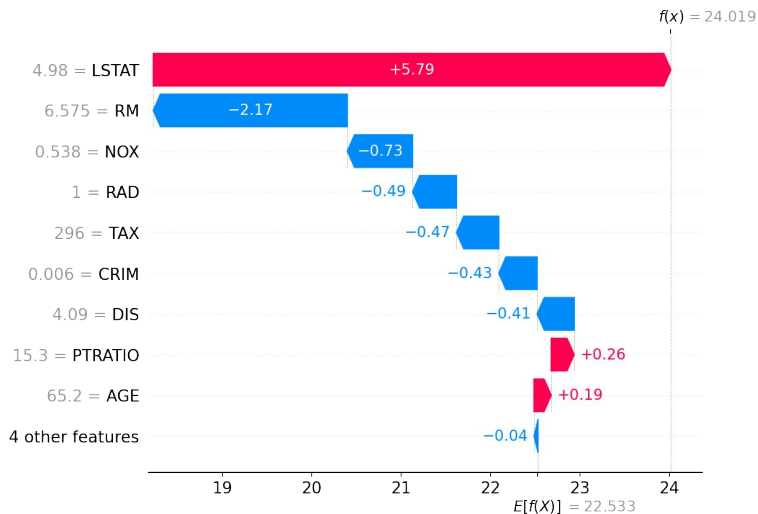
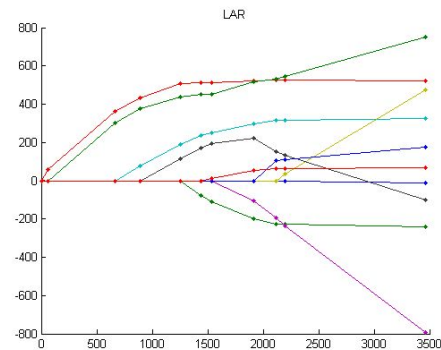
Feature selection

Select subset of existing features to use in further modelling

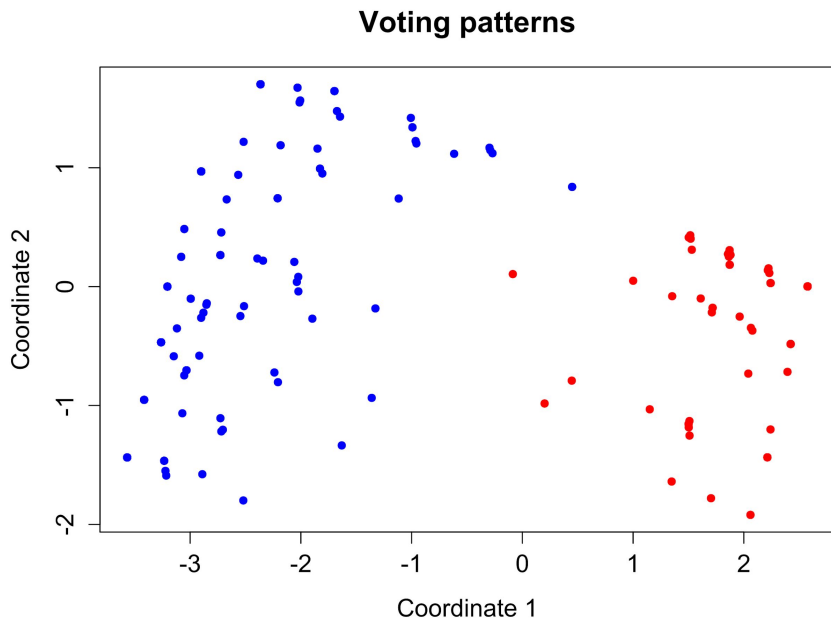
Usually is based on some supervised method

Examples:

- [stepwise regression](#)
- [LARS](#)
- [SHAP values](#)
- etc...



Multidimensional Scaling (MDS)



[Voting patterns in the United States House of Representatives](#)

Goal:

Linearly embed to given lower space

Solution:

PCA

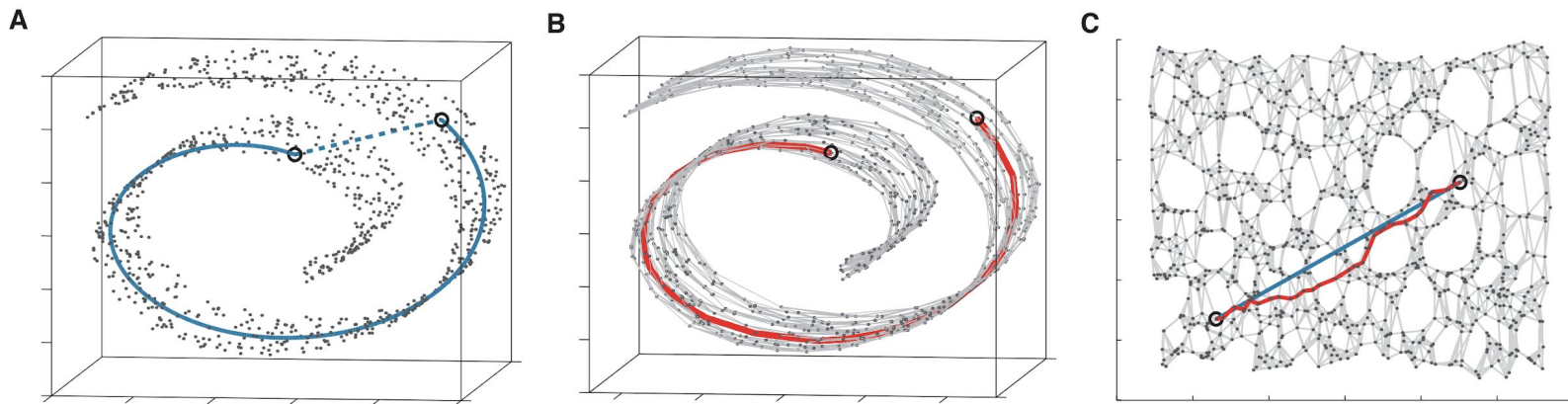
$$L = ||D_x - D_y||_2 \rightarrow \min_{y=Ax}$$

$$y = \Lambda^{1/2} V^T$$

Params: p - target dimensionality

Also could be non-linear

Isomap



Now make distances geodesic!
And measure distances on the produced graph

Params:
n - number of neighbours to connect
p - dimensionality of manifold

[A Global Geometric Framework for Nonlinear Dimensionality Reduction, Tenenbaum et al., Science, 2002.](#)

Isomap algorithm



Step

- | | | |
|---|--------------------------------------|--|
| 1 | Construct neighborhood graph | Define the graph G over all data points by connecting points i and j if [as measured by $d_x(i,j)$] they are closer than ϵ (ϵ -Isomap), or if i is one of the K nearest neighbors of j (K -Isomap). Set edge lengths equal to $d_x(i,j)$. |
| 2 | Compute shortest paths | Initialize $d_G(i,j) = d_x(i,j)$ if i,j are linked by an edge; $d_G(i,j) = \infty$ otherwise. Then for each value of $k = 1, 2, \dots, N$ in turn, replace all entries $d_G(i,j)$ by $\min\{d_G(i,j), d_G(i,k) + d_G(k,j)\}$. The matrix of final values $D_G = \{d_G(i,j)\}$ will contain the shortest path distances between all pairs of points in G (16, 19). |
| 3 | Construct d -dimensional embedding | Let λ_p be the p -th eigenvalue (in decreasing order) of the matrix $\tau(D_G)$ (17), and v_p^i be the i -th component of the p -th eigenvector. Then set the p -th component of the d -dimensional coordinate vector \mathbf{y}_i equal to $\sqrt{\lambda_p} v_p^i$. |

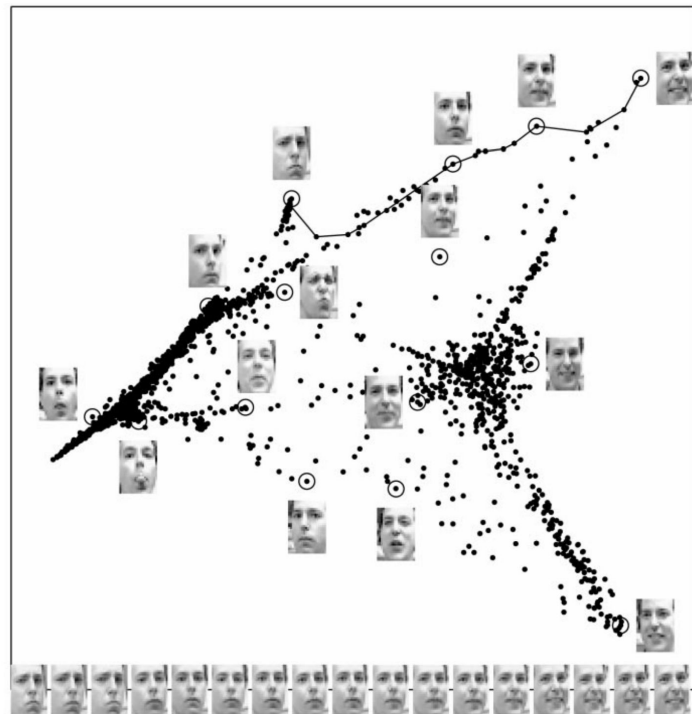
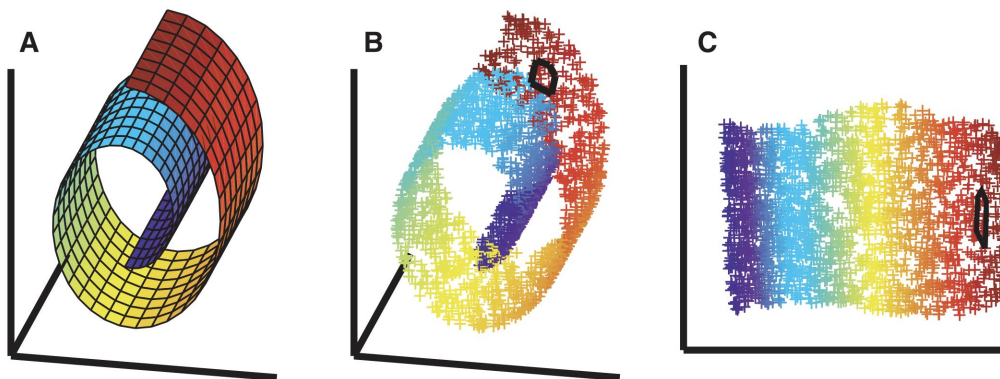
17. The operator τ is defined by $\tau(D) = -HS/2$, where S is the matrix of squared distances $\{S_{ij} = D_{ij}^2\}$, and H is the "centering matrix" $\{H_{ij} = \delta_{ij} - 1/N\}$ (13).

Locally linear embedding (LLE)



Smooth manifold locally approximated with hyperplane. Linear pieces are stitched together.

[Nonlinear Dimensionality Reduction by Locally Linear Embedding, Roweis et al., Science, 2000](#)



LLE algorithm



1. estimate point by its K neighbours

$$\varepsilon(W) = \sum_{i=1}^n \left\| x_i - \sum_{j=1}^K W_{ij} x_j \right\|^2$$

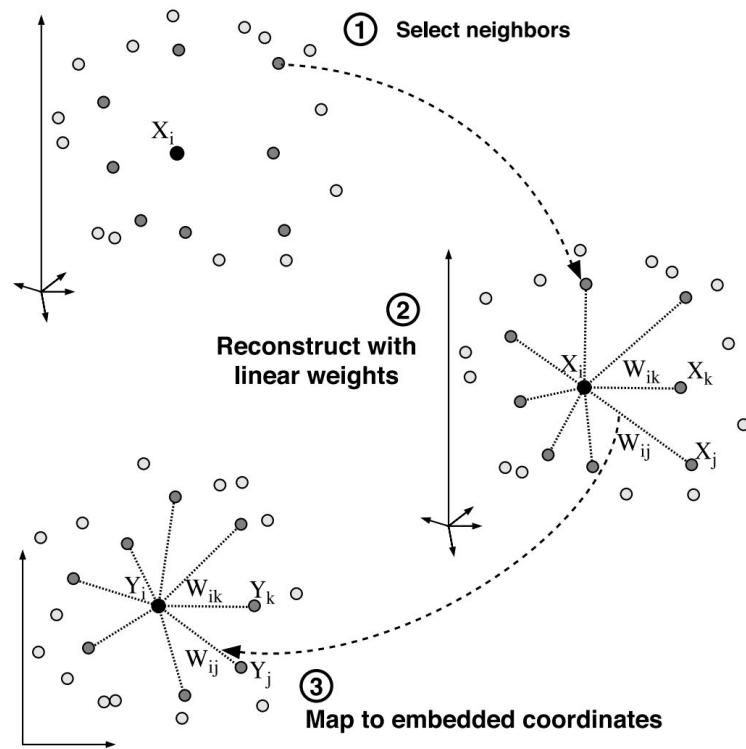
2. Estimate new points based on known relations

$$\Phi(Y) = \sum_{i=1}^n \left\| y_i - \sum_{j=1}^K W_{ij} y_j \right\|^2$$

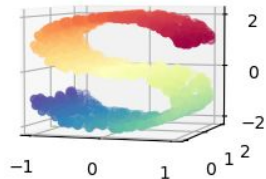
Params:

n - number of neighbours to connect

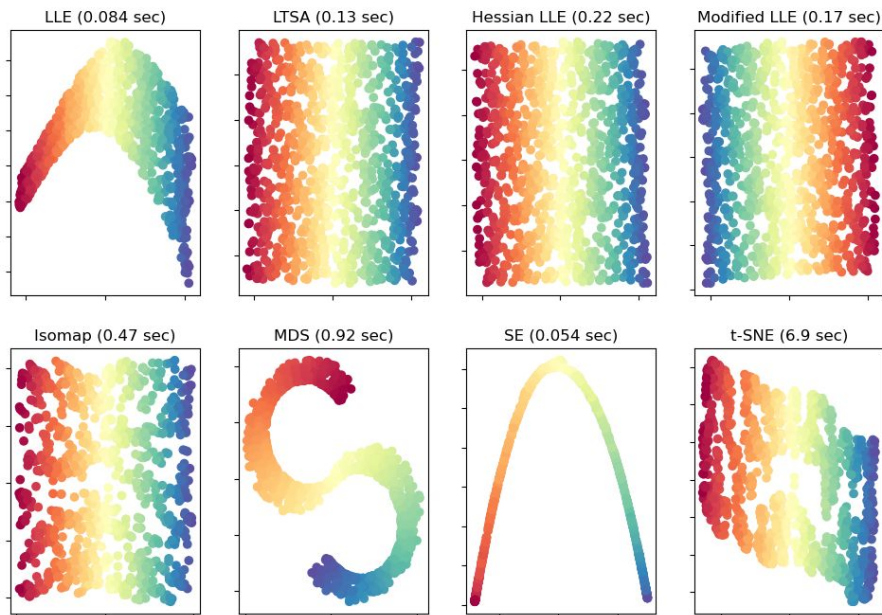
p - dimensionality of manifold



Many more



Manifold Learning with 1000 points, 10 neighbors

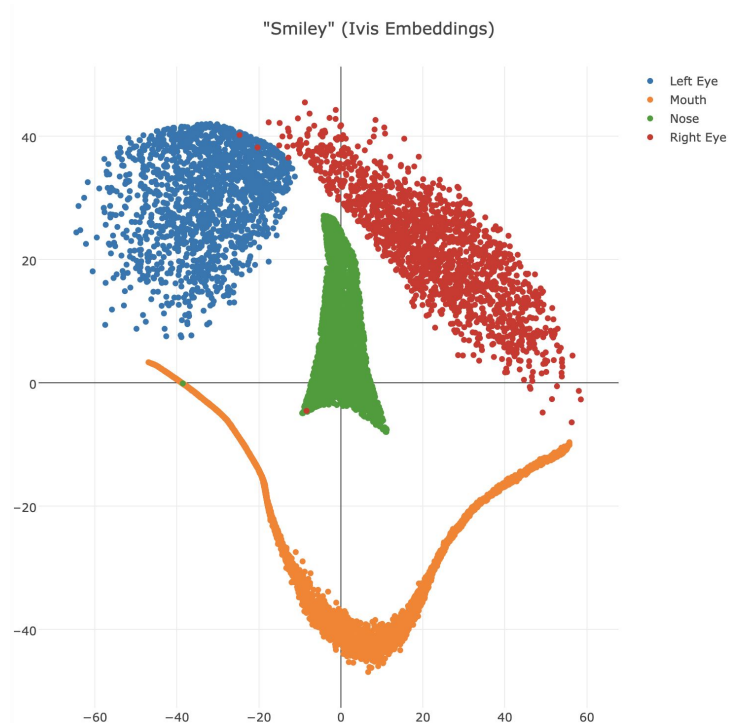
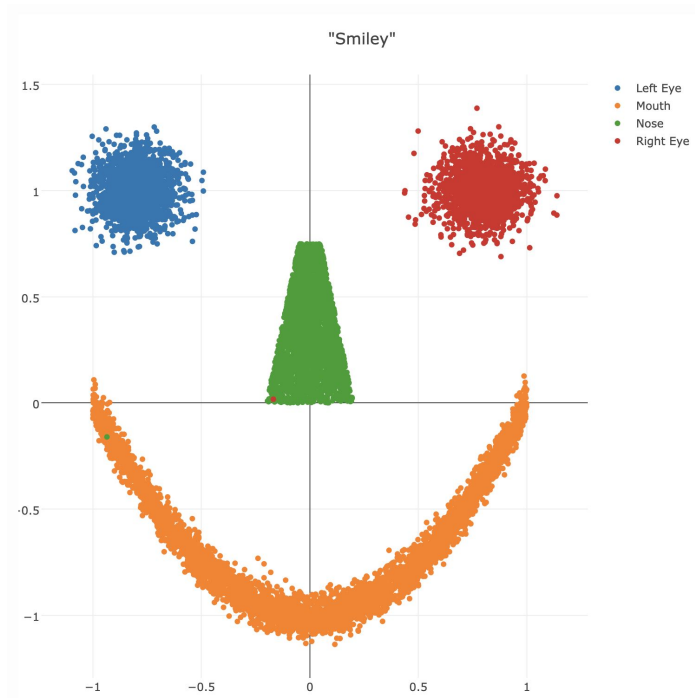


- Hessian Eigenmapping
- Spectral Embedding
- Local Tangent Space Alignment
- Riemannian Geometry
- UMAP
-

Read more:

[sklearn manifold methods](#)
[sklearn signals decomposition](#)

Next level: Neural Networks



[UMAP vs Ivis embeddings](#)

t-SNE



t-distributed Stochastic Neighbor Embedding

SNE

[Stochastic Neighbor Embedding, Hinton et al., NIPS, 2002](#)

Stochastic Neighbor Embedding



Convert pairwise distances to probabilities, preserve probabilities through the spaces

$$p_{j|i} = \frac{\exp(-\frac{\|x_i - x_j\|^2}{2\sigma_i^2})}{\sum_{k \neq i} \exp(-\frac{\|x_i - x_k\|^2}{2\sigma_i^2})}$$

asymmetric probability
of object i chooses j as its neighbour

$$q_{j|i} = \frac{\exp(-\|y_i - y_j\|^2)}{\sum_{k \neq i} \exp(-\|y_i - y_k\|^2)}$$

the same in target space

Let's construct embedding s.t. these distributions are close.

What are close distributions?

Kullback–Leibler divergence



$$D_{KL}(P \parallel Q) = \sum_{i,j} p_{j|i} \log \frac{p_{j|i}}{q_{j|i}}$$



ЧОТ
ПОДОЗРИТЕЛЬНО

Suspiciously similar to Shannon entropy

[Learn more](#)



SNE problem

$$p_{j|i} = \frac{\exp(-\frac{\|x_i - x_j\|^2}{2\sigma_i^2})}{\sum_{k \neq i} \exp(-\frac{\|x_i - x_k\|^2}{2\sigma_i^2})}$$

$$q_{j|i} = \frac{\exp(-\|y_i - y_j\|^2)}{\sum_{k \neq i} \exp(-\|y_i - y_k\|^2)}$$

$$D_{KL}(P \parallel Q) \rightarrow \min_Y$$

t-distributed SNE



Patches over SNE:

1. choose common variance
2. make distributions symmetric

$$p_{ij} = \frac{\exp(-\|x_i - x_j\|^2 / 2\sigma^2)}{\sum_{k \neq l} \exp(-\|x_k - x_l\|^2 / 2\sigma^2)}$$

$$p_{ij}^s = \frac{p_{ij} + p_{ji}}{2N}$$

[Visualizing Data using t-SNE,](#)
[Maaten, Hinton, 2008, JMLR](#)

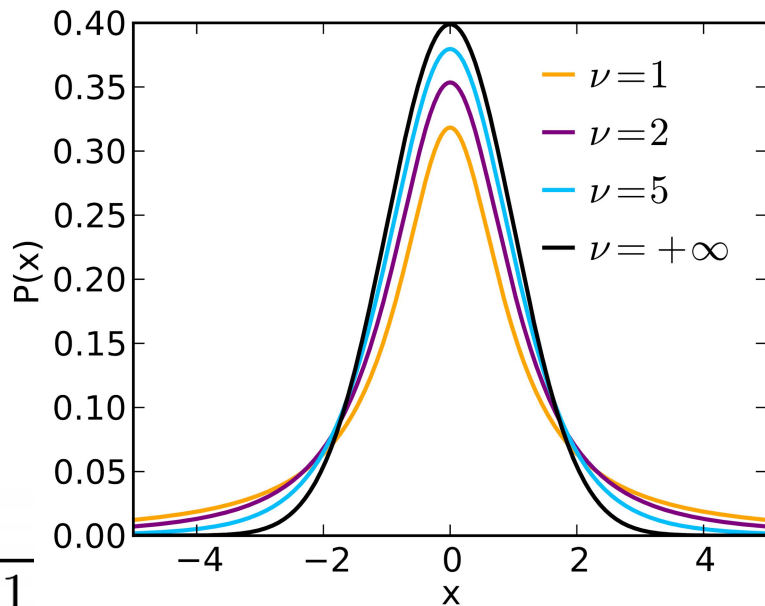
t-distributed SNE



Patches over SNE:

1. choose common variance
2. make distributions symmetric
3. make it decrease faster than Gaussian
(use [Student's t-distribution](#))

$$q_{ij} = \frac{(1 + \|y_i - y_j\|^2)^{-1}}{\sum_{k \neq l} (1 + \|y_k - y_l\|^2)^{-1}}$$



t-SNE problem



$$p_{ij} = \frac{\exp(-\|x_i - x_j\|^2 / 2\sigma^2)}{\sum_{k \neq l} \exp(-\|x_k - x_l\|^2 / 2\sigma^2)} \quad p_{ij}^s = \frac{p_{ij} + p_{ji}}{2N}$$

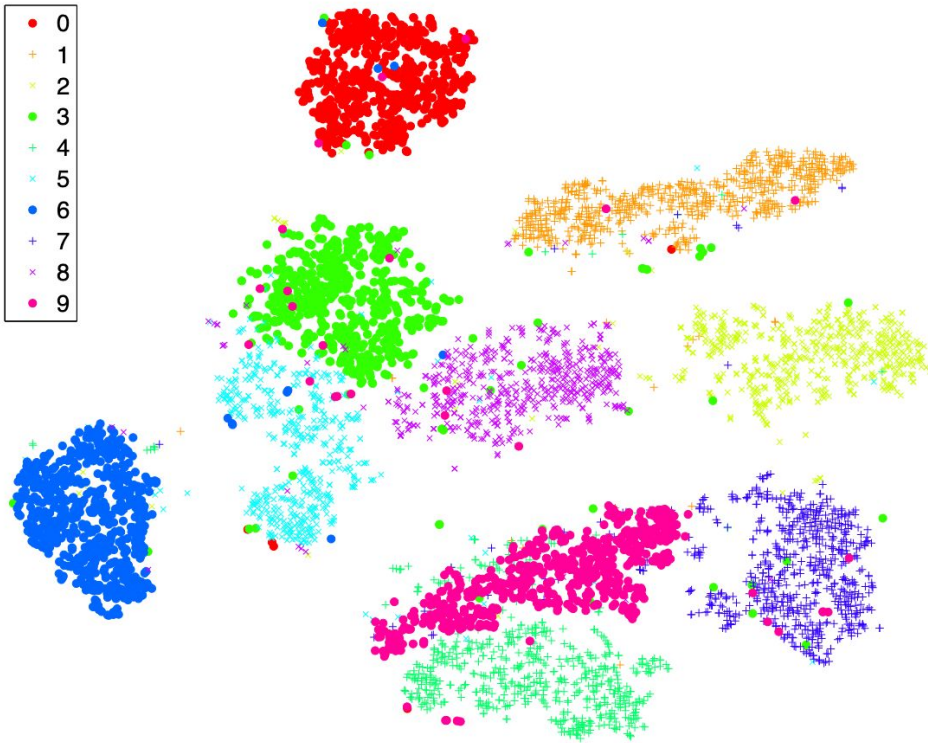
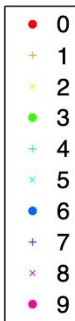
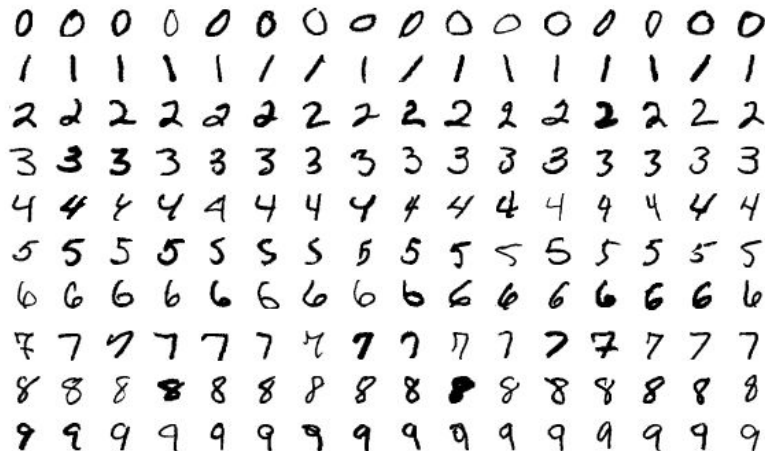
$$q_{ij} = \frac{(1 + \|y_i - y_j\|^2)^{-1}}{\sum_{k \neq l} (1 + \|y_k - y_l\|^2)^{-1}}$$

$$D_{KL}(P \parallel Q) \rightarrow \min_Y$$

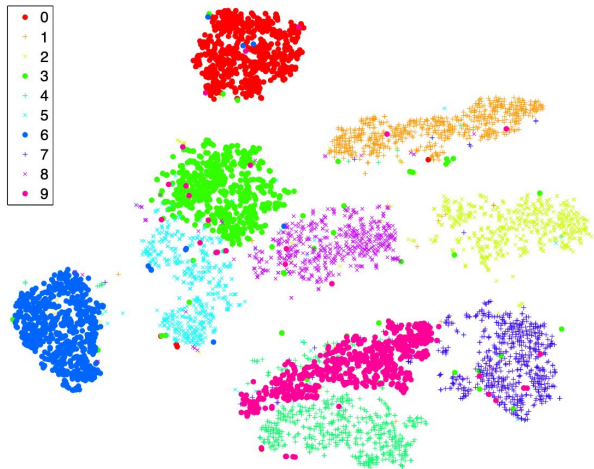
Result: nice and light visualizations



t-SNE on [MNIST dataset](#)



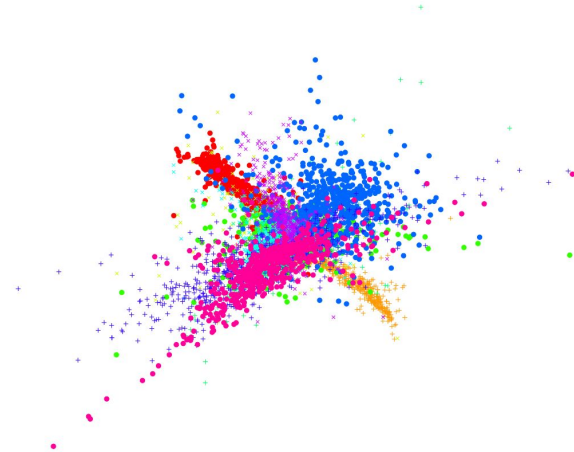
Comparison



t-SNE



Isomap



LLE

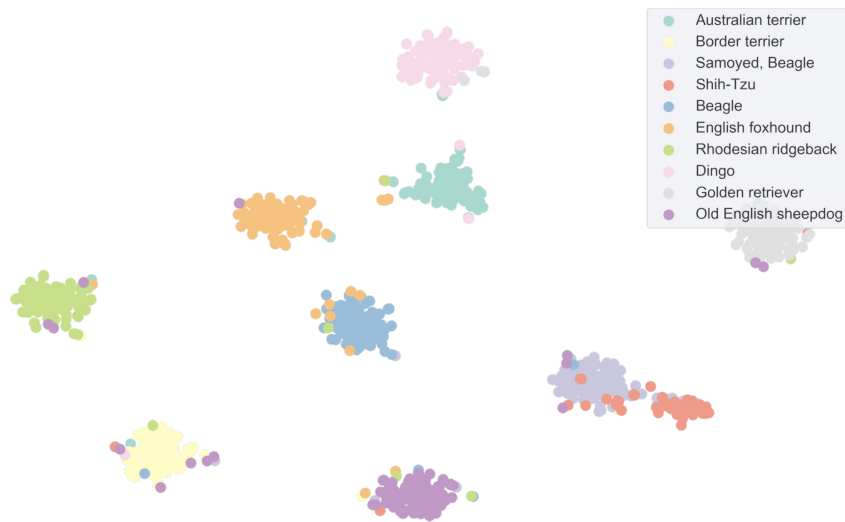
Real life example



MDS (PCA) on faces
embeddings

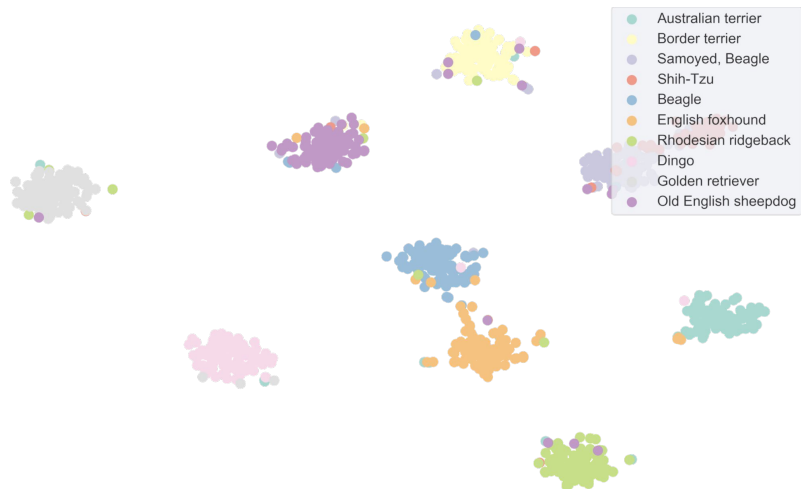
[image source](#)

Real life example



t-SNE on ArcFace

t-SNE on CosFace

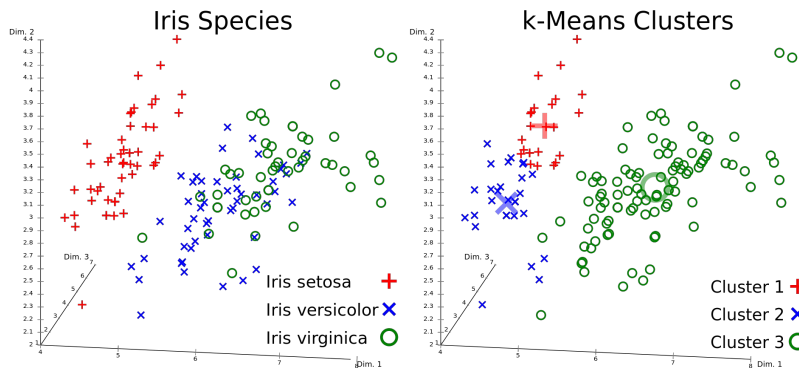


Clustering

girafe
ai

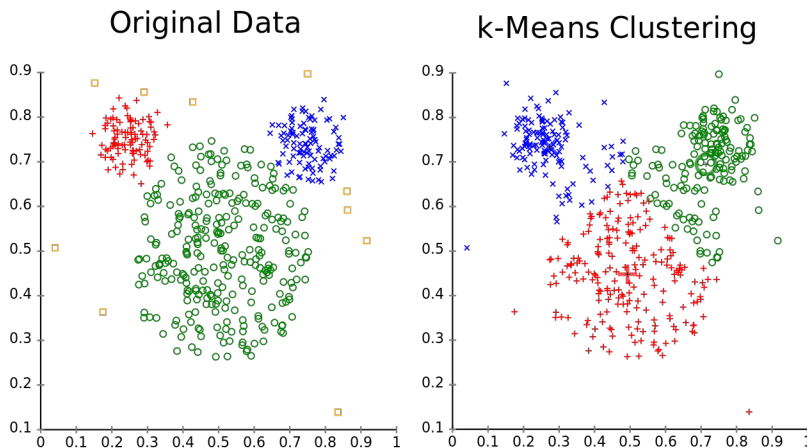
03

k-means



Based on K nearest neighbours algorithm

1. Init clusters centers randomly
2. Define current cluster of an object as a nearest center
3. Calculate new cluster center as a mean of all objects in cluster
4. Repeat from p. 2 until convergence



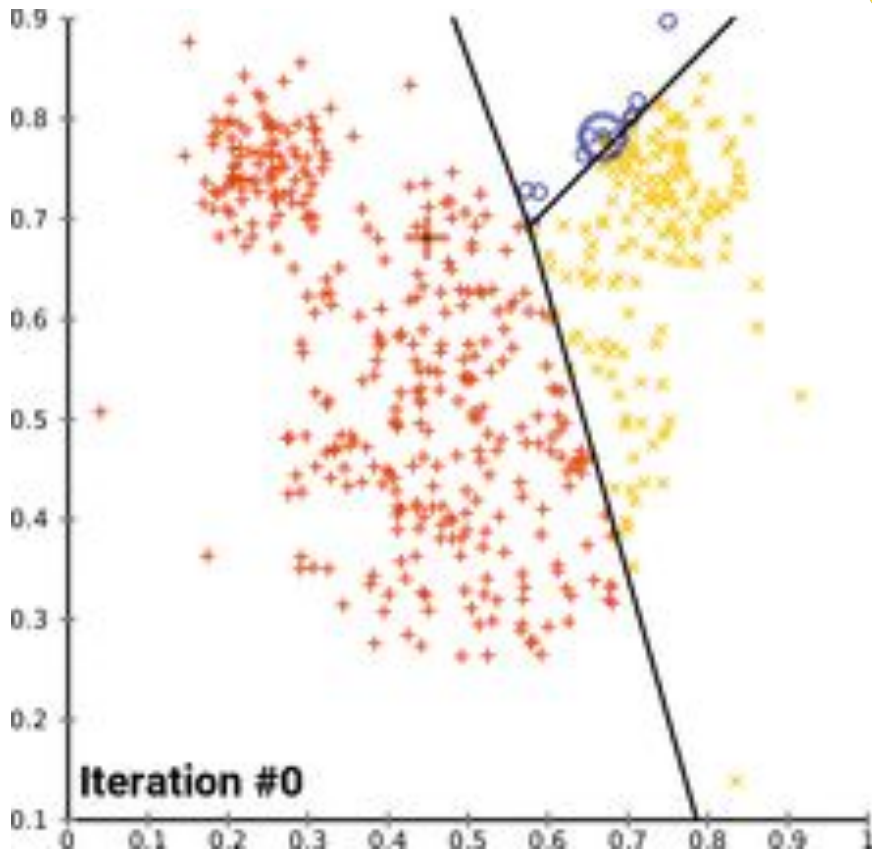
k-means

Params:

k - number of clusters

Advanced version: k-means++

[The Advantages of Careful Seeding.](#)
[Arthur, Vassilvitskii, 2007, ACM-SIAM](#)
[SODA](#)



DBSCAN

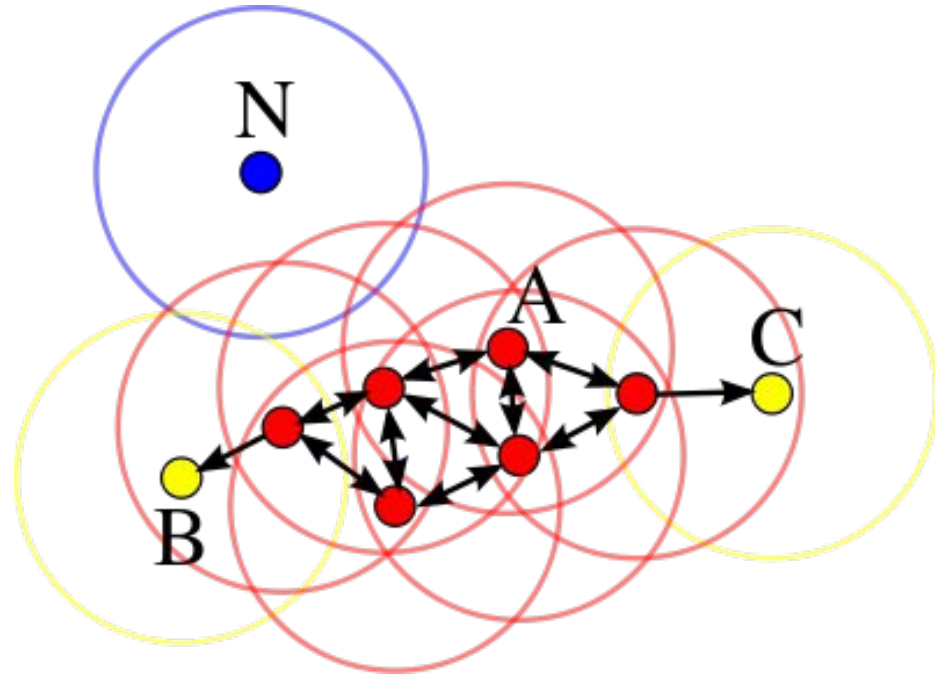


Density-Based Spatial Clustering of
Applications with Noise

Split all data points into 3 groups:

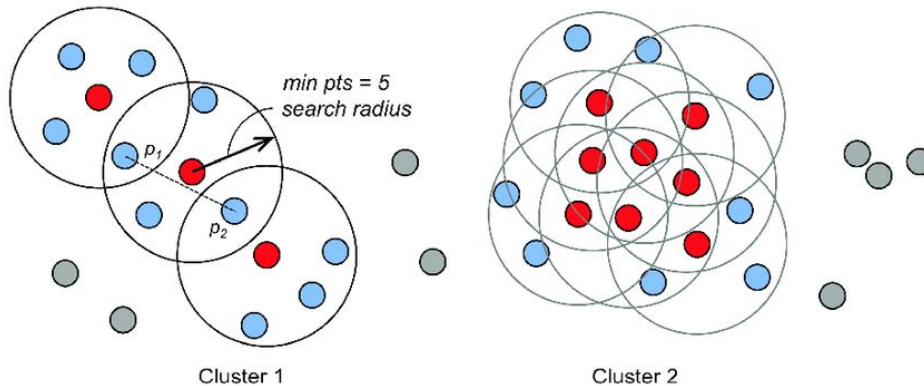
1. Core (red)
2. Border (yellow)
3. Noise (blue)

Core point has at least k other points in
 ϵ -neighbourhood



[A density-based algorithm for discovering clusters in large spatial databases with noise, Ester et al., 1996, KDD-96](#)

DBSCAN



Any two core or border points in ϵ -neighbourhood noted as connected points

Two points both connected to a common point also defined connected (transitivity)

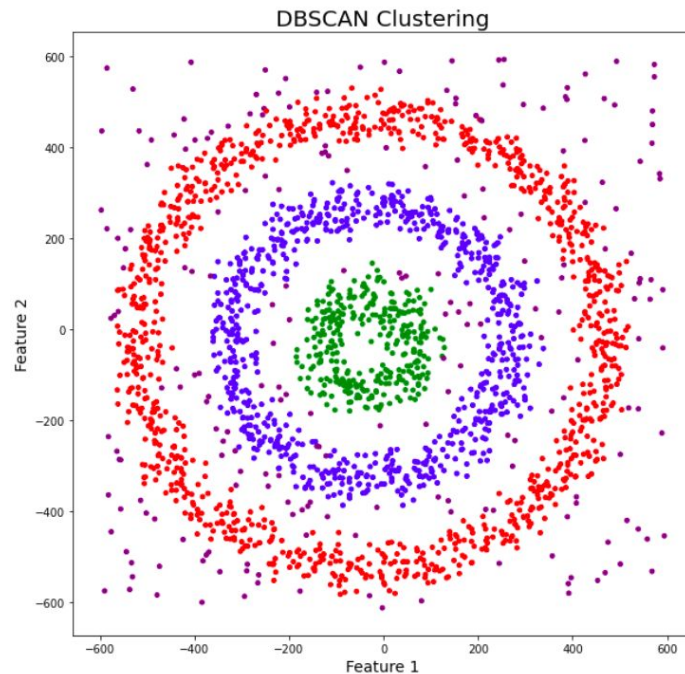
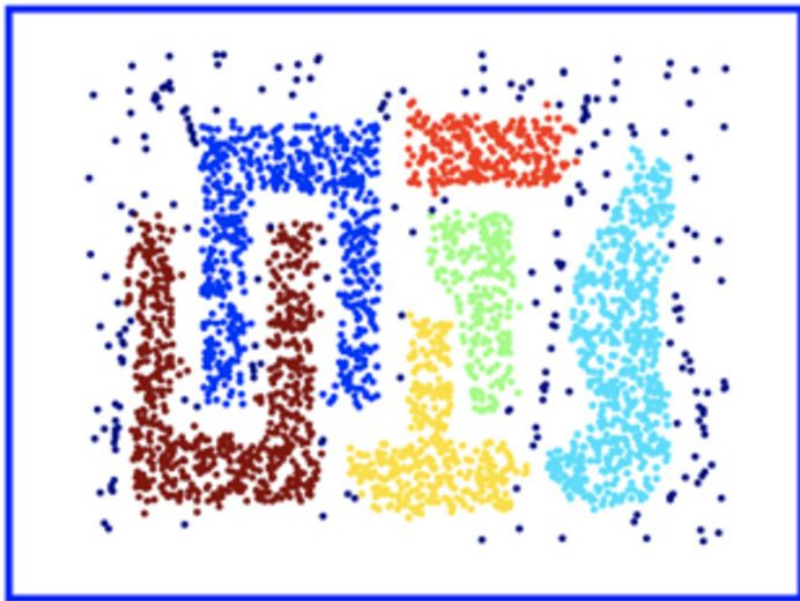
Cluster is defined as maximum connected set of points

Params:

ϵ - radius of neighbourhood

k - minimal number of neighbours of core point

DBSCAN examples

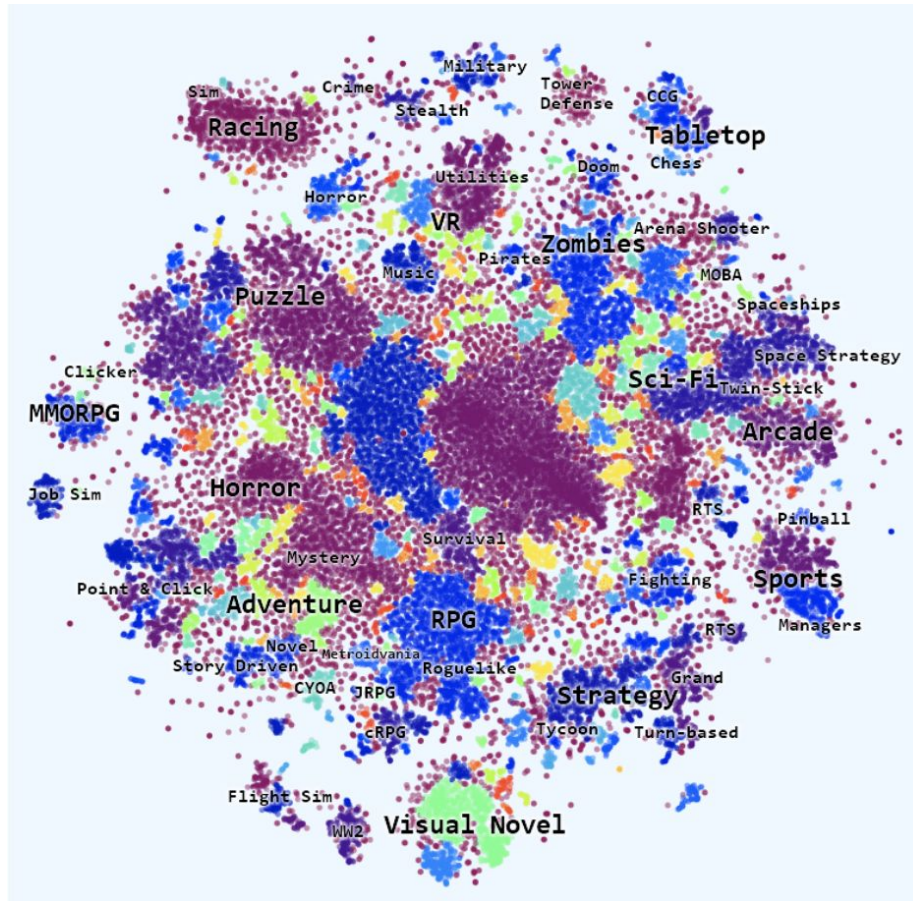


DBSCAN examples

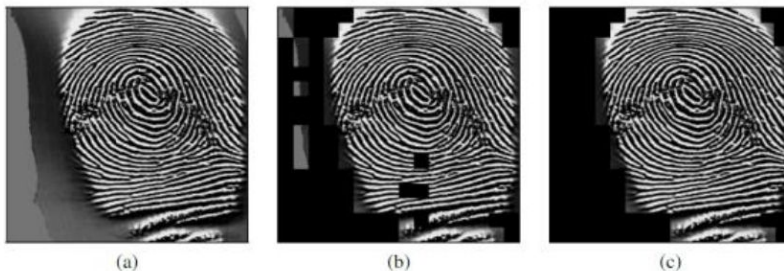
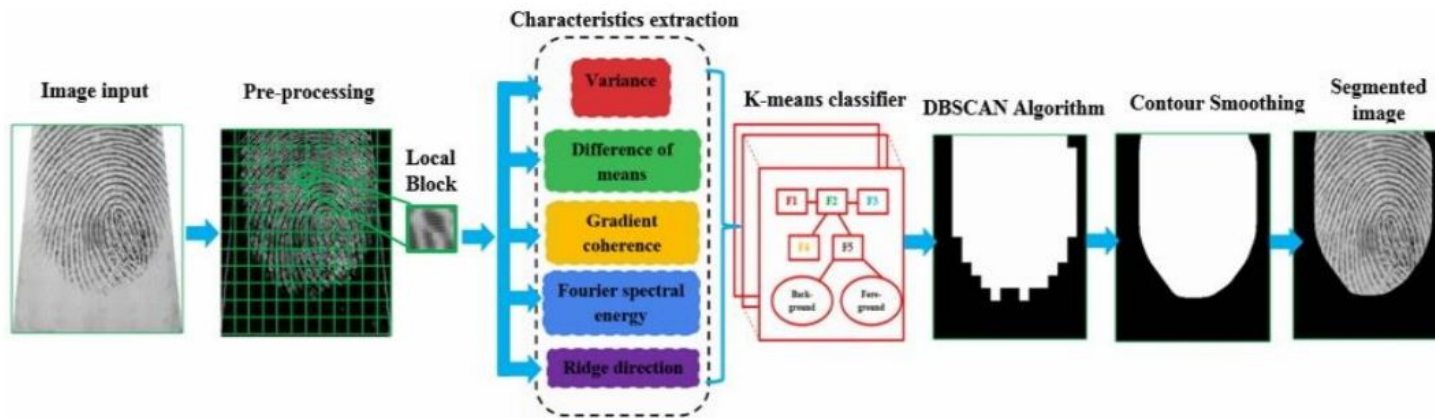


DBSCAN on t-SNE output
to analyze embeddings (Doc2vec)
of video games

[image source](#)



DBSCAN examples



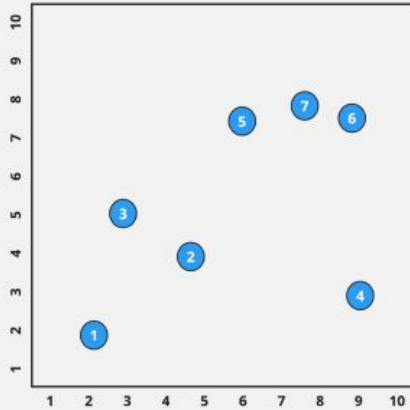
a - original, b - k-means, c - DBSCAN

[Improving of Fingerprint Segmentation Images Based on K-MEANS and DBSCAN Clustering, Cherrat et al., 2019, IJECE](#)

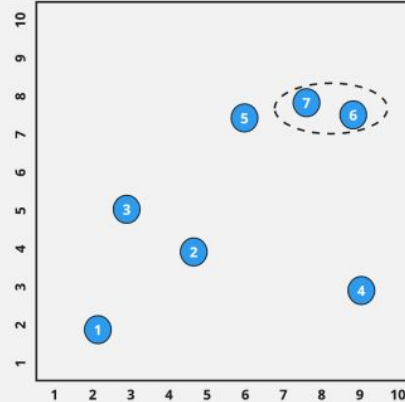
Hierarchical clustering



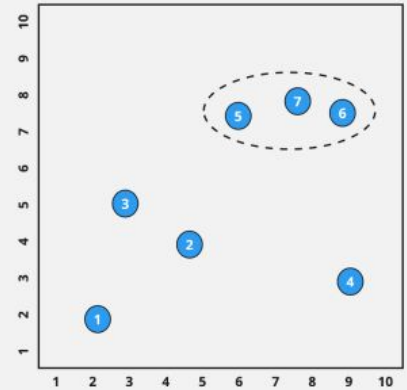
Step 01



Step 02

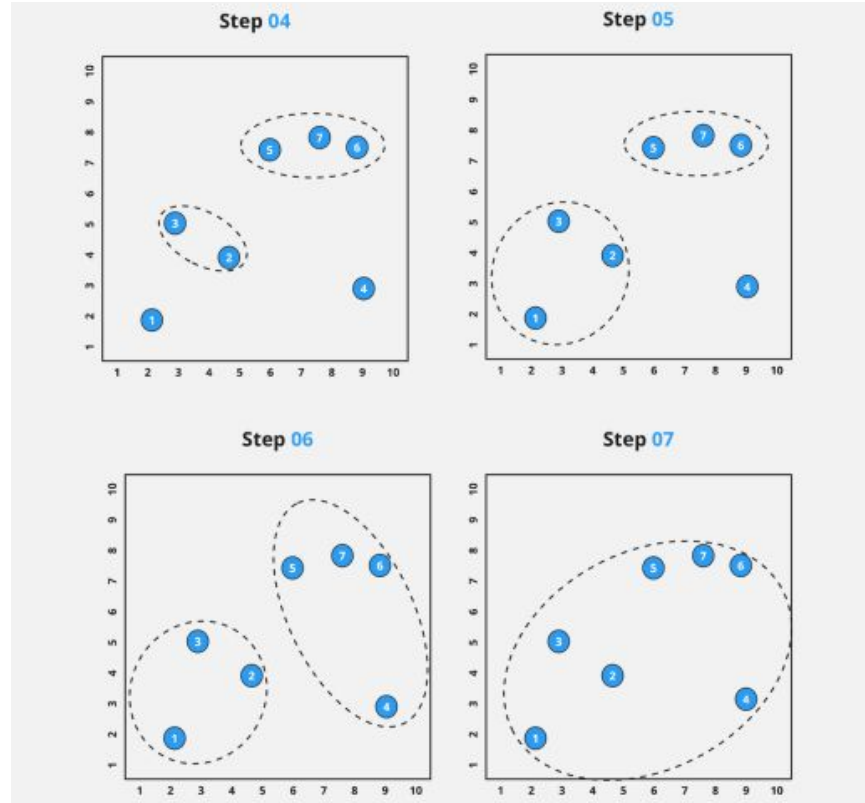


Step 03

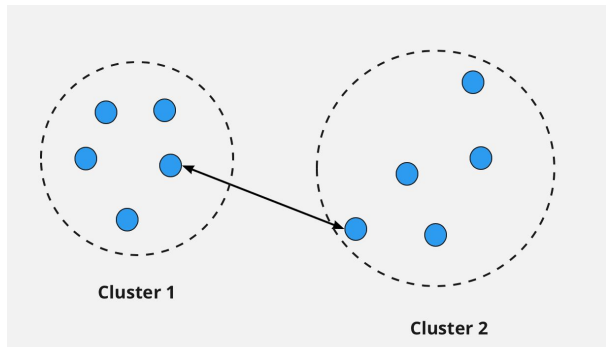


[image source](#)

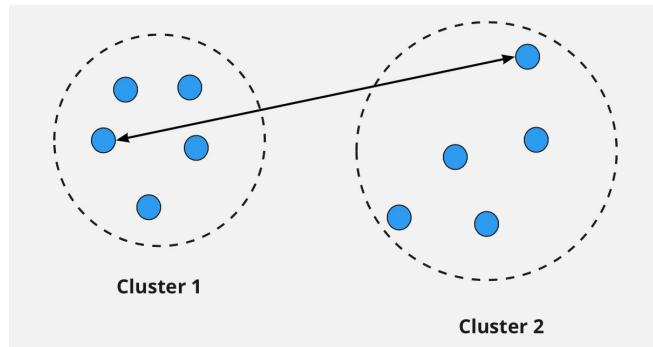
Hierarchical clustering



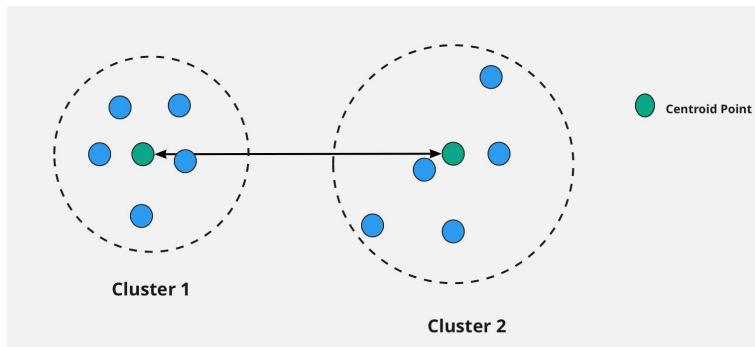
Distance between clusters



Closest point



Farthest point



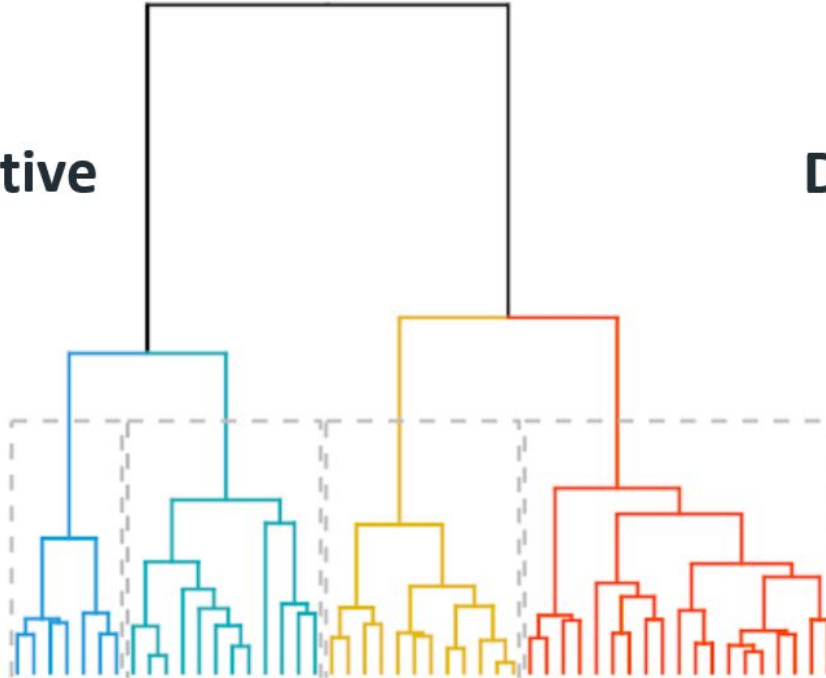
Centroid

Dendrogram

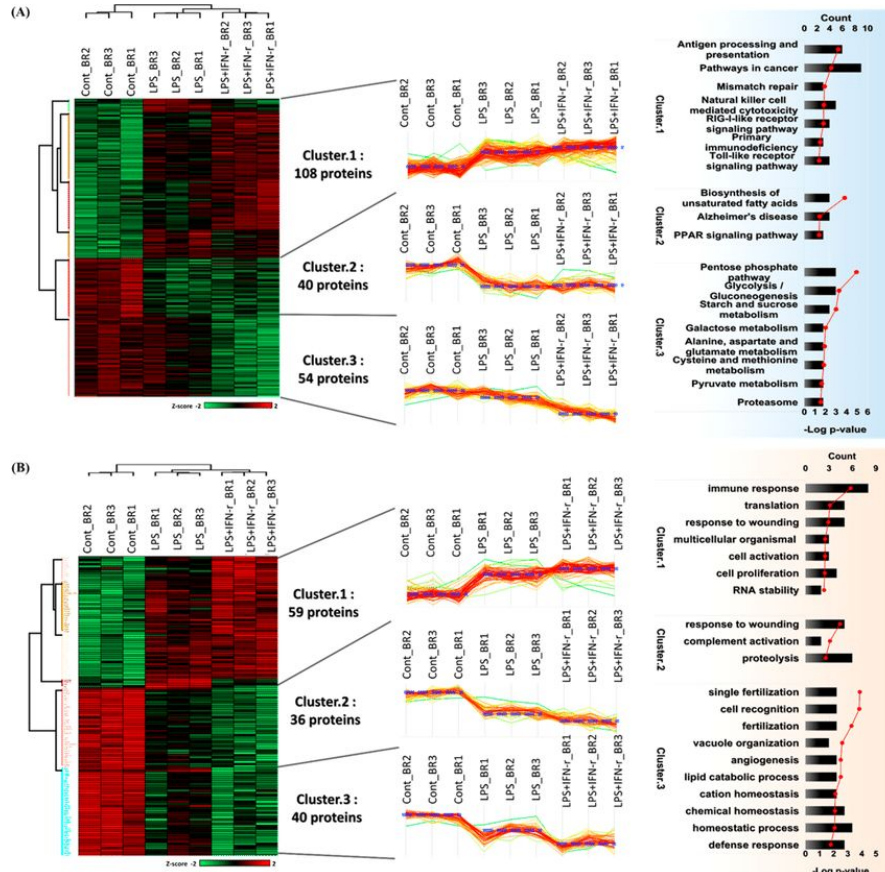


Agglomerative

Divisive



Dendrograms example

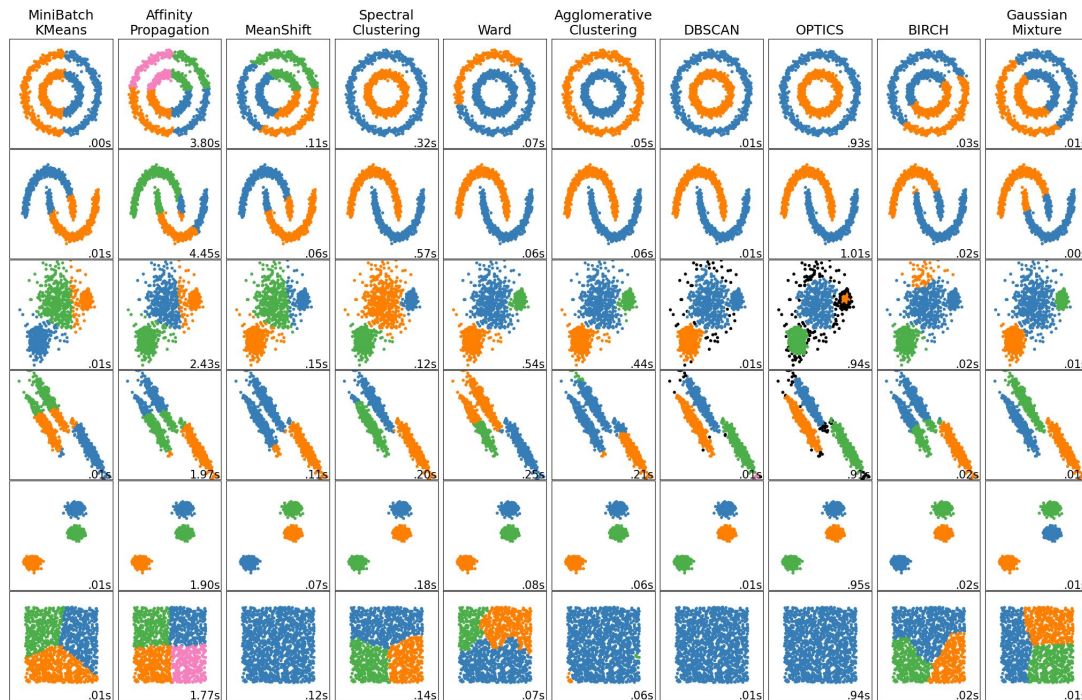


Hierarchical clustering and dendrograms often used in bioinformatics to visualize heatmaps of molecules interactions

[Image source](#)

Practical case: [seriation](#), [historical overview](#), [Python implementation for images](#)

Many more



Read more:

[sklearn huge overview](#)

[HDBSCAN \(hierarchy + DBSCAN\)](#)

[timeseries clusterization](#) (ru)

Clustering metrics



- Label based
 - Rand index
 - Mutual Information
 - Homogeneity
 - Completeness
 - V-measure
 - ...
- Label free
 - Silhouette Coefficient
 - Calinski-Harabasz Index
 - Davies-Bouldin Index
 - ...

[Nice overview \[ru\]](#)

[Detailed explanations \(sklearn docs\)](#)

Clusters found by HDBSCAN

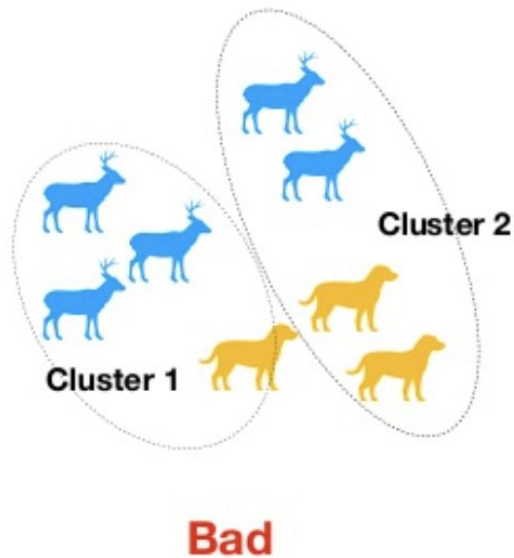
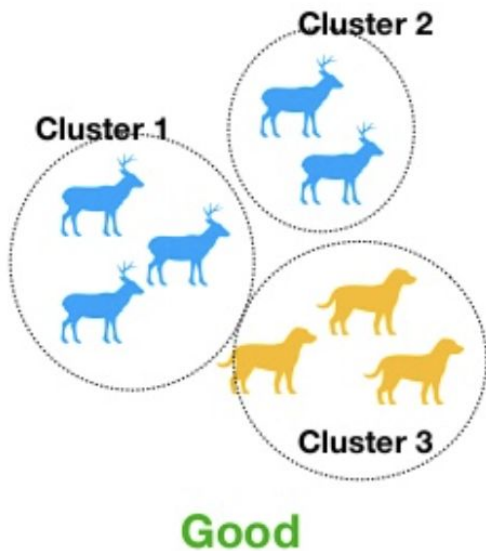


[image source](#)

Homogeneity



Each cluster contains only members of a single class



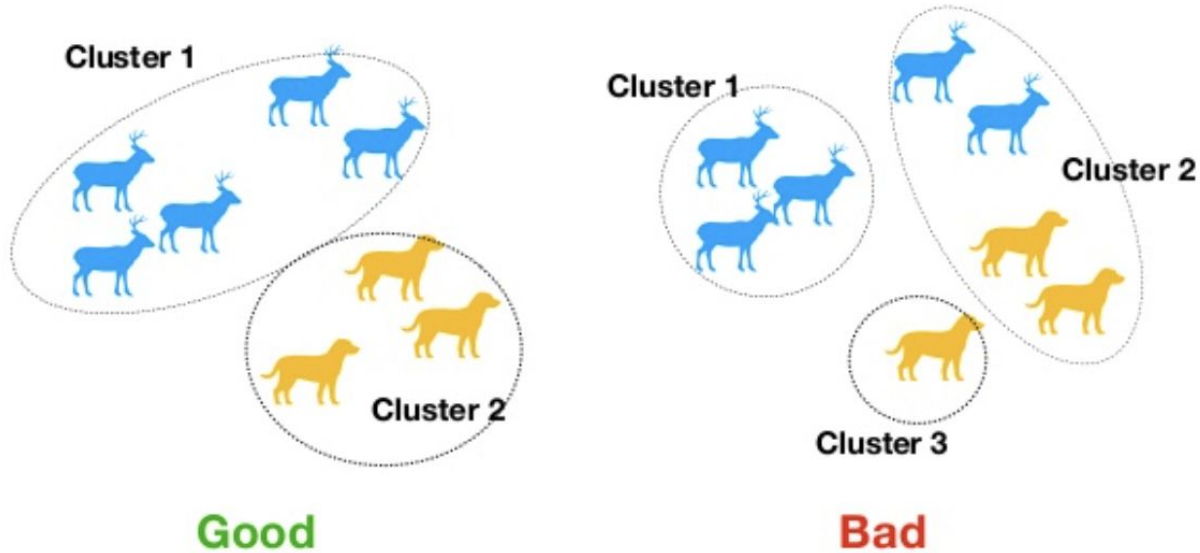
[image source](#)

and great slides on topic

Completeness



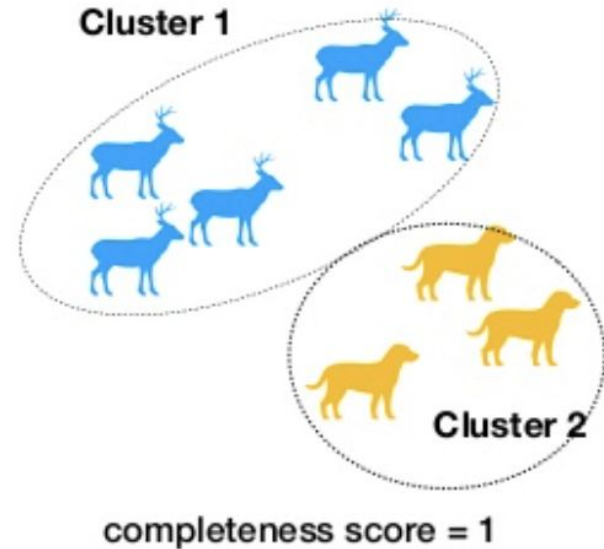
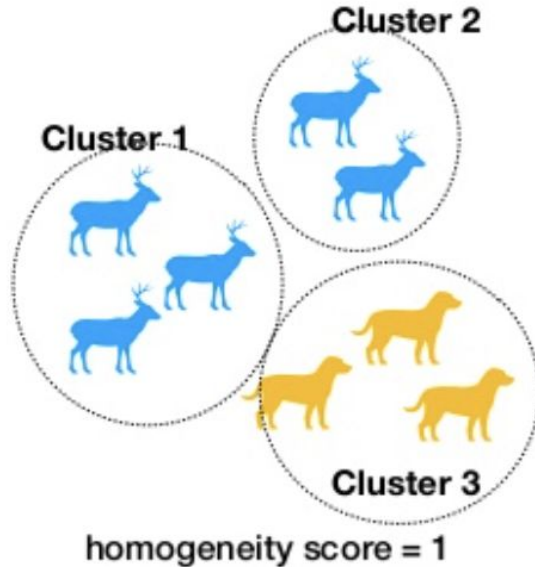
all members of a given class are assigned to the same cluster



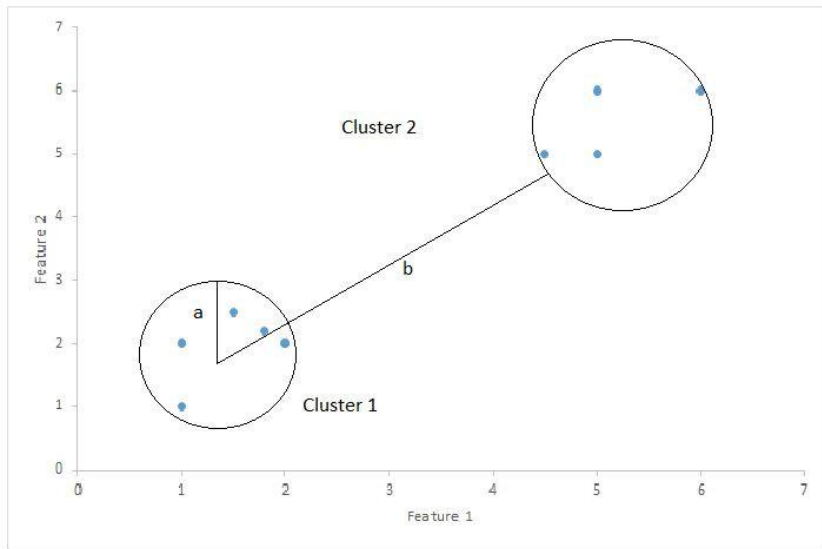
V-measure



geometric mean of Homogeneity and Completeness



Silhouette coefficient



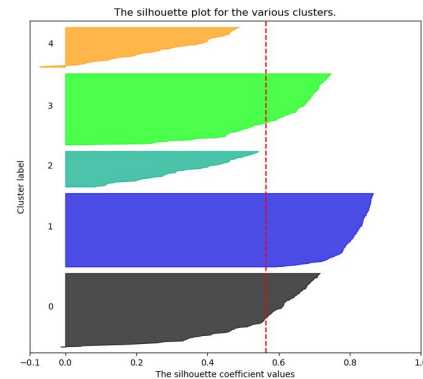
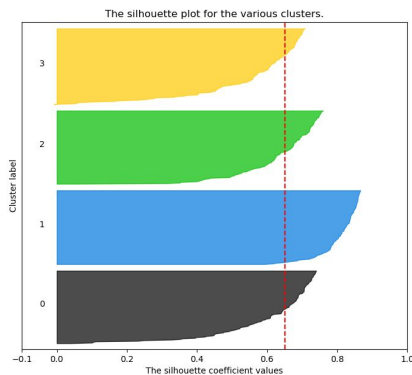
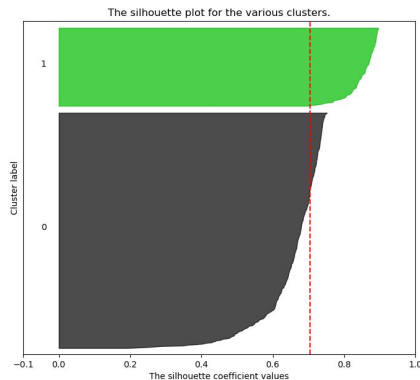
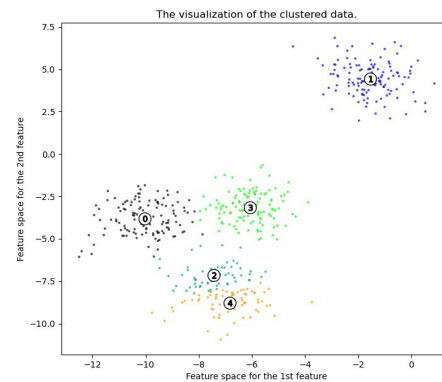
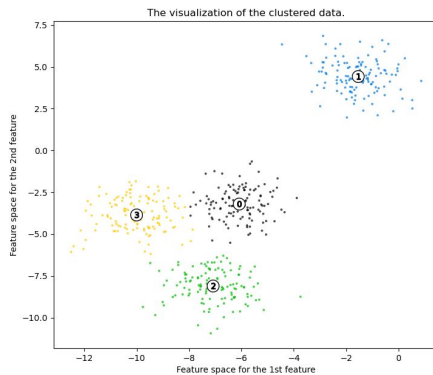
[image source](#)

a: mean distance to points
in the *same cluster*

b: mean distance to points
in the *next nearest cluster*

$$s_i = \frac{b_i - a_i}{\max(a_i, b_i)}$$

Silhouette analysis

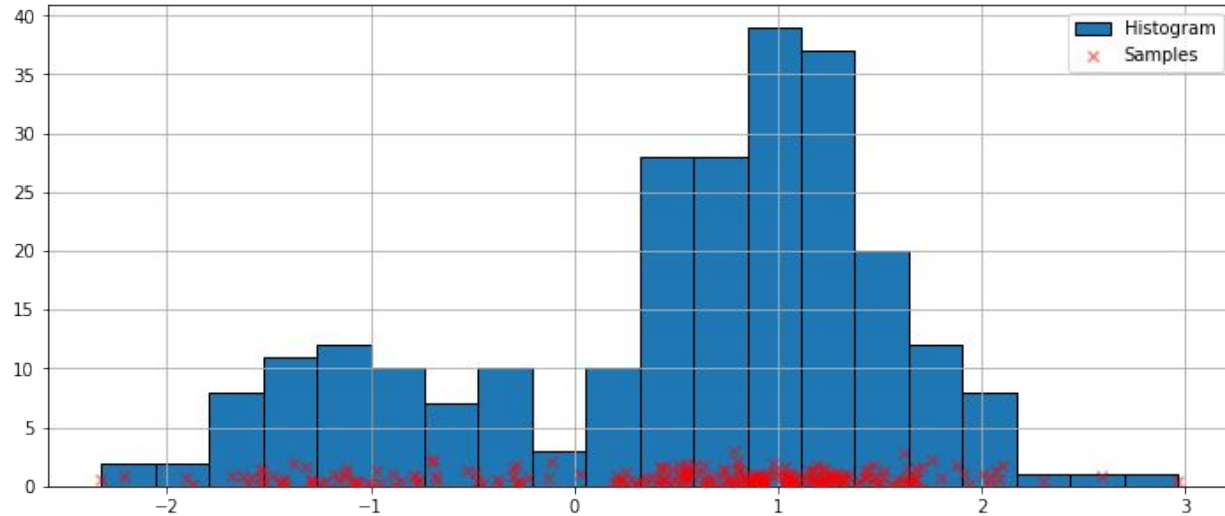


Density estimation

girafe
ai

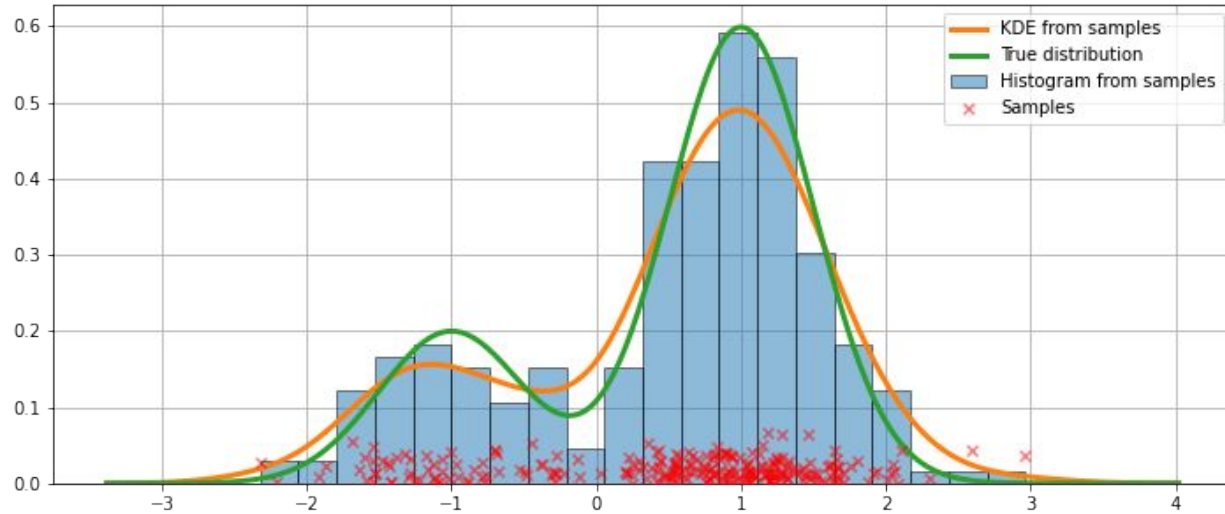
04

Kernel density estimation

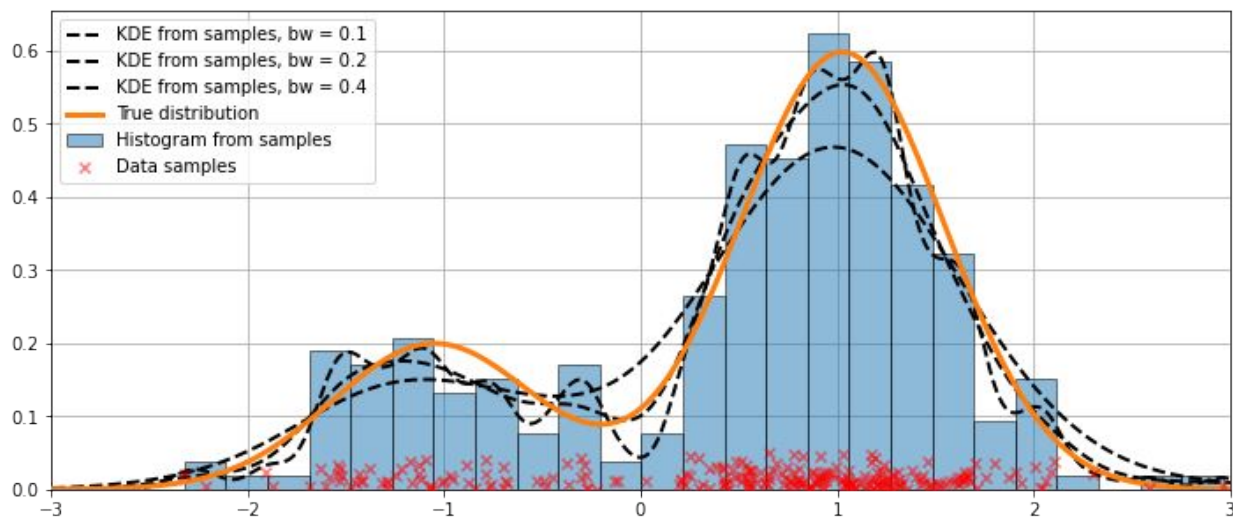


[statsmodels documentation example](#)

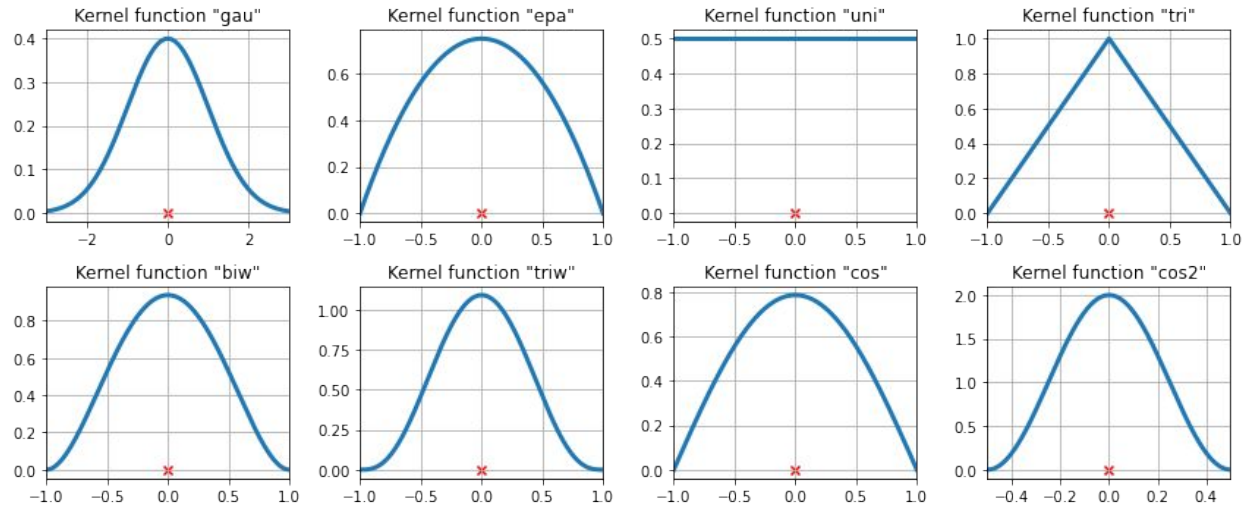
Kernel density estimation



Window size



Kernel types



Revise



- Geometrical machine learning
 - Dimensionality curse
 - Manifold assumption
- Dimensionality reduction
 - Feature selection
 - Multidimensional Scaling (MDS)
 - Isomap
 - Locally linear embedding (LLE)
 - t-SNE
- Clustering
 - k-means
 - DBSCAN
 - Hierarchical clustering
 - metrics
- Density estimation
 - Kernel density estimation

Thanks for attention!

Questions?

girafe
ai





Notable links

1. [Good lecture on MDS, Isomap, LLE](#)
2. [Lecture on t-SNE](#) (this one is good too)
3. [Slides about clusterization](#)
4. [Metrics in clusterization](#)
5. [Slides about ICA](#)
6. [More clustering methods](#) (in Russian)